

Lecture Slides for INTRODUCTION TO MACHINE LEARNING 3RD EDITION

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CHAPTER 8: NONPARAMETRIC METHODS

Nonparametric Estimation

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- Parametric (single global model), semiparametric (small number of local models)
- Nonparametric: Similar inputs have similar outputs
- Functions (pdf, discriminant, regression) change smoothly
- Keep the training data; "let the data speak for itself"
- Given x, find a small number of closest training instances and interpolate from these
- Aka lazy/memory-based/case-based/instancebased learning

Density Estimation

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- Given the training set $X = \{x^t\}_t$ drawn iid from p(x)
- Divide data into bins of size h
- □ Histogram: $\hat{p}(x) = \frac{\#\{x^t \text{ in the same bin as } x\}}{Nh}$
- □ Naive estimator: $\hat{p}(x) = \frac{\#\{x - h < x^t \le x + h\}}{2Nh}$
 - or

$$\hat{p}(x) = \frac{1}{Nh} \sum_{t=1}^{N} w \left(\frac{x - x^{t}}{h} \right) \quad w(u) = \begin{cases} 1/2 & \text{if } |u| < 1\\ 0 & \text{otherwise} \end{cases}$$





Naive estimator: h=2

Kernel Estimator

□ Kernel function, e.g., Gaussian kernel:

$$K(u) = \frac{1}{\sqrt{2\pi}} \exp\left[-\frac{u^2}{2}\right]$$

Kernel estimator (Parzen windows)

$$\hat{p}(x) = \frac{1}{Nh} \sum_{t=1}^{N} K\left(\frac{x-x^{t}}{h}\right)$$



k-Nearest Neighbor Estimator

Instead of fixing bin width h and counting the number of instances, fix the instances (neighbors) k and check bin width

$$\hat{p}(x) = \frac{k}{2Nd_k(x)}$$

 $d_k(x)$, distance to kth closest instance to x



Multivariate Data

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Kernel density estimator

$$\hat{o}(\mathbf{x}) = \frac{1}{Nh^d} \sum_{t=1}^N K\left(\frac{\mathbf{x} - \mathbf{x}^t}{h}\right)$$

Multivariate Gaussian kernel

spheric
$$\mathcal{K}(\mathbf{u}) = \left(\frac{1}{\sqrt{2\pi}}\right)^{d} \exp\left[-\frac{\|\mathbf{u}\|^{2}}{2}\right]$$

ellipsoid $\mathcal{K}(\mathbf{u}) = \frac{1}{(2\pi)^{d/2} |\mathbf{S}|^{1/2}} \exp\left[-\frac{1}{2}\mathbf{u}^{T}\mathbf{S}^{-1}\mathbf{u}\right]$

Nonparametric Classification

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- **Estimate** $p(\mathbf{x} | C_i)$ and use Bayes' rule
- Kernel estimator

$$\hat{p}(\mathbf{x} | C_i) = \frac{1}{N_i h^d} \sum_{t=1}^N \mathcal{K}\left(\frac{\mathbf{x} - \mathbf{x}^t}{h}\right) r_i^t \quad \hat{P}(C_i) = \frac{N_i}{N}$$
$$g_i(\mathbf{x}) = \hat{p}(\mathbf{x} | C_i) \hat{P}(C_i) = \frac{1}{N h^d} \sum_{t=1}^N \mathcal{K}\left(\frac{\mathbf{x} - \mathbf{x}^t}{h}\right) r_i^t$$

□ *k*-NN estimator

$$\hat{p}(\mathbf{x} | C_i) = \frac{k_i}{N_i V^k(\mathbf{x})} \quad \hat{P}(C_i | \mathbf{x}) = \frac{\hat{p}(\mathbf{x} | C_i)\hat{P}(C_i)}{\hat{p}(\mathbf{x})} = \frac{k_i}{k}$$

Condensed Nearest Neighbor

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- \Box Time/space complexity of k-NN is O (N)
- Find a subset Z of X that is small and is accurate in classifying X (Hart, 1968)



Condensed Nearest Neighbor

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Incremental algorithm: Add instance if needed

$$\begin{array}{l} \mathcal{Z} \leftarrow \emptyset \\ \text{Repeat} \\ \text{For all } \boldsymbol{x} \in \mathcal{X} \text{ (in random order)} \\ \text{Find } \boldsymbol{x}' \in \mathcal{Z} \text{ s.t. } \| \boldsymbol{x} - \boldsymbol{x}' \| = \min_{\boldsymbol{x}^j \in \mathcal{Z}} \| \boldsymbol{x} - \boldsymbol{x}^j \| \\ \text{If } \text{class}(\boldsymbol{x}) \neq \text{class}(\boldsymbol{x}') \text{ add } \boldsymbol{x} \text{ to } \mathcal{Z} \end{array}$$
Until \mathcal{Z} does not change

Distance-based Classification

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- \Box Find a distance function $D(\mathbf{x}^r, \mathbf{x}^s)$ such that
 - if x^r and x^s belong to the same class, distance is small and if they belong to different classes, distance is large
- Assume a parametric model and learn its parameters using data, e.g.,

$$\mathcal{D}(\boldsymbol{x}, \boldsymbol{x}^t | \mathbf{M}) = (\boldsymbol{x} - \boldsymbol{x}^t)^T \mathbf{M} (\boldsymbol{x} - \boldsymbol{x}^t)$$

Learning a Distance Function

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- The three-way relationship between distances, dimensionality reduction, and feature extraction.
 M=L^TL is dxd and L is kxd

$$\mathcal{D}(\boldsymbol{x}, \boldsymbol{x}^t | \mathbf{M}) = (\boldsymbol{x} - \boldsymbol{x}^t)^T \mathbf{M}(\boldsymbol{x} - \boldsymbol{x}^t) = (\boldsymbol{x} - \boldsymbol{x}^t)^T \mathbf{L}^T \mathbf{L}(\boldsymbol{x} - \boldsymbol{x}^t)$$

= $(\mathbf{L}(\boldsymbol{x} - \boldsymbol{x}^t))^T (\mathbf{L}(\boldsymbol{x} - \boldsymbol{x}^t)) = (\mathbf{L}\boldsymbol{x} - \mathbf{L}\boldsymbol{x}^t)^T (\mathbf{L}\boldsymbol{x} - \mathbf{L}\boldsymbol{x}^t))$
= $(\boldsymbol{z} - \boldsymbol{z}^t)^T (\boldsymbol{z} - \boldsymbol{z}^t) = \|\boldsymbol{z} - \boldsymbol{z}^t\|^2$

- Similarity-based representation using similarity scores
- Large-margin nearest neighbor (chapter 13)



Euclidean distance (circle) is not suitable,

Mahalanobis distance using an **M** (ellipse) is suitable.

After the data is projected along **L**, Euclidean distance can be used.

Outlier Detection

- Find outlier/novelty points
- Not a two-class problem because outliers are very few, of many types, and seldom labeled
- Instead, one-class classification problem: Find instances that have low probability
- In nonparametric case: Find instances far away from other instances

Local Outlier Factor

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$$\text{LOF}(\boldsymbol{x}) = \frac{d_k(\boldsymbol{x})}{\sum_{\boldsymbol{s} \in \mathcal{N}(\boldsymbol{x})} d_k(\boldsymbol{s}) / |\mathcal{N}(\boldsymbol{x})|}$$



Nonparametric Regression

- Aka smoothing models
- Regressogram

$$\hat{g}(x) = \frac{\sum_{t=1}^{N} b(x, x^{t}) r^{t}}{\sum_{t=1}^{N} b(x, x^{t})}$$

where

 $b(x, x^{t}) = \begin{cases} 1 & \text{if } x^{t} \text{ is in the same bin with } x \\ 0 & \text{otherwise} \end{cases}$





Running Mean/Kernel Smoother

Running mean smoother



where

$$w(u) = \begin{cases} 1 & \text{if}|u| < 1 \\ 0 & \text{otherwise} \end{cases}$$

Running line smoother



where K() is Gaussian
Additive models (Hastie and Tibshirani, 1990)







How to Choose k or h?

- When k or h is small, single instances matter; bias is small, variance is large (undersmoothing): High complexity
- As k or h increases, we average over more instances and variance decreases but bias increases (oversmoothing): Low complexity
- \Box Cross-validation is used to finetune k or h.

