

Lecture Slides for
**INTRODUCTION
TO
MACHINE
LEARNING**
3RD EDITION

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CHAPTER 6:

DIMENSIONALITY REDUCTION

Why Reduce Dimensionality?

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- Reduces time complexity: Less computation
- Reduces space complexity: Fewer parameters
- Saves the cost of observing the feature
- Simpler models are more robust on small datasets
- More interpretable; simpler explanation
- Data visualization (structure, groups, outliers, etc) if plotted in 2 or 3 dimensions

Feature Selection vs Extraction

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- Feature selection: Choosing $k < d$ important features, ignoring the remaining $d - k$

Subset selection algorithms

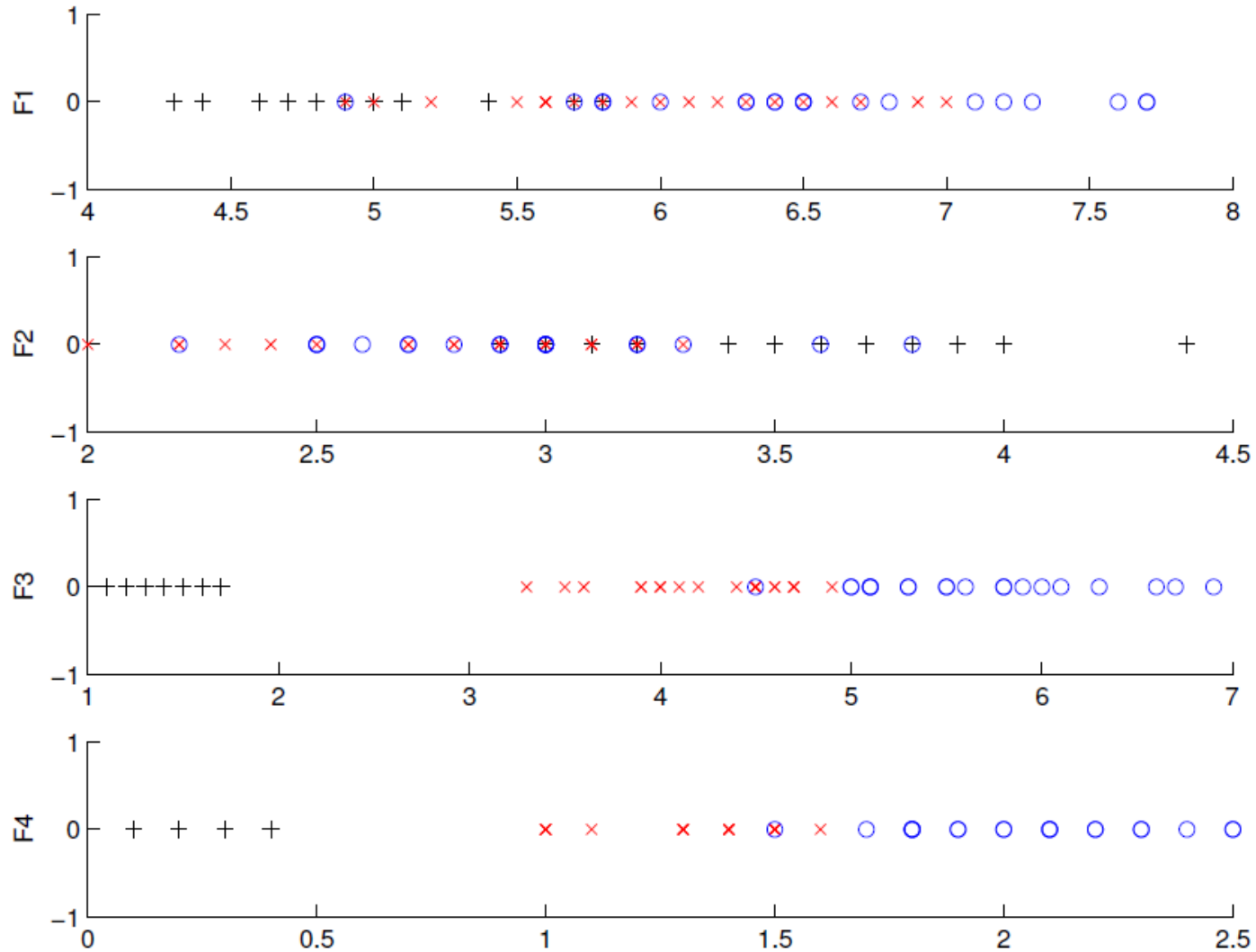
- Feature extraction: Project the original $x_i, i = 1, \dots, d$ dimensions to new $k < d$ dimensions, $z_j, j = 1, \dots, k$

Subset Selection

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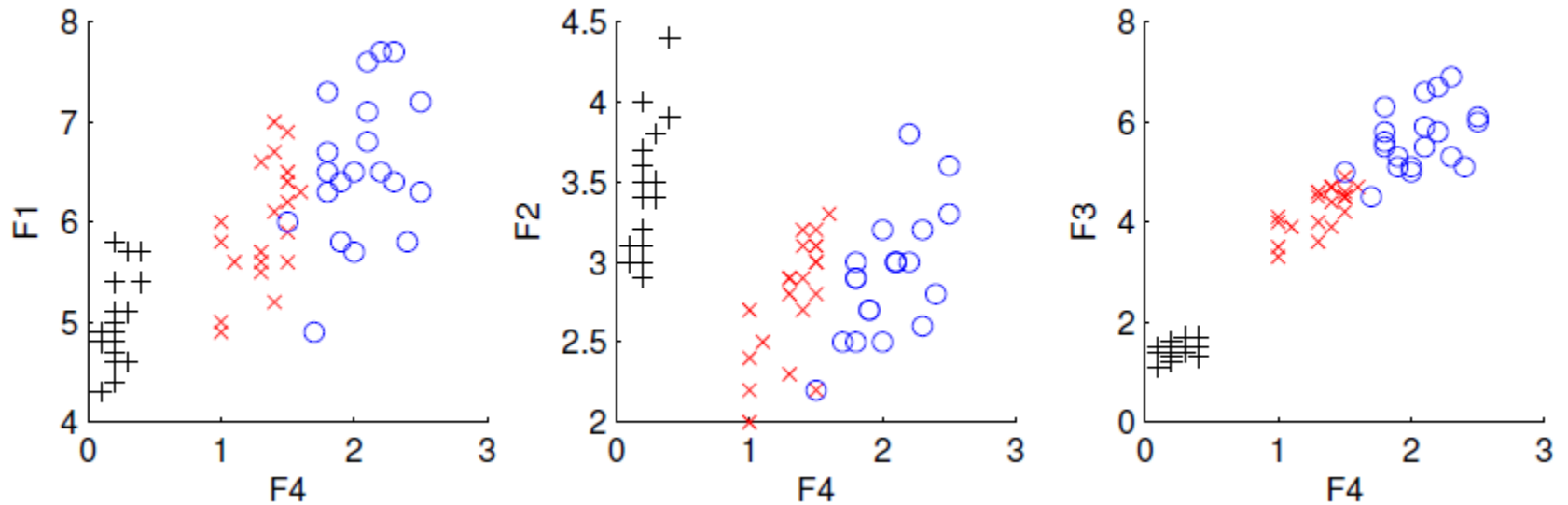
- There are 2^d subsets of d features
- Forward search: Add the best feature at each step
 - ▣ Set of features F initially \emptyset .
 - ▣ At each iteration, find the best new feature
$$j = \operatorname{argmin}_i E (F \cup x_i)$$
 - ▣ Add x_j to F if $E (F \cup x_j) < E (F)$
- Hill-climbing $O(d^2)$ algorithm
- Backward search: Start with all features and remove one at a time, if possible.
- Floating search (Add k , remove l)

Iris data: Single feature



Chosen

Iris data: Add one more feature to F4



Chosen

Principal Components Analysis

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- Find a low-dimensional space such that when \mathbf{x} is projected there, information loss is minimized.
- The projection of \mathbf{x} on the direction of \mathbf{w} is: $z = \mathbf{w}^T \mathbf{x}$
- Find \mathbf{w} such that $\text{Var}(z)$ is maximized

$$\begin{aligned}\text{Var}(z) &= \text{Var}(\mathbf{w}^T \mathbf{x}) = E[(\mathbf{w}^T \mathbf{x} - \mathbf{w}^T \boldsymbol{\mu})^2] \\ &= E[(\mathbf{w}^T \mathbf{x} - \mathbf{w}^T \boldsymbol{\mu})(\mathbf{w}^T \mathbf{x} - \mathbf{w}^T \boldsymbol{\mu})] \\ &= E[\mathbf{w}^T (\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T \mathbf{w}] \\ &= \mathbf{w}^T E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T] \mathbf{w} = \mathbf{w}^T \boldsymbol{\Sigma} \mathbf{w}\end{aligned}$$

where $\text{Var}(\mathbf{x}) = E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T] = \boldsymbol{\Sigma}$

- Maximize $\text{Var}(z)$ subject to $||\mathbf{w}|| = 1$

$$\max_{\mathbf{w}_1} \mathbf{w}_1^T \Sigma \mathbf{w}_1 - \alpha (\mathbf{w}_1^T \mathbf{w}_1 - 1)$$

$\Sigma \mathbf{w}_1 = \alpha \mathbf{w}_1$ that is, \mathbf{w}_1 is an eigenvector of Σ

Choose the one with the largest eigenvalue for $\text{Var}(z)$ to be max

- Second principal component: Max $\text{Var}(z_2)$, s.t., $||\mathbf{w}_2|| = 1$ and orthogonal to \mathbf{w}_1

$$\max_{\mathbf{w}_2} \mathbf{w}_2^T \Sigma \mathbf{w}_2 - \alpha (\mathbf{w}_2^T \mathbf{w}_2 - 1) - \beta (\mathbf{w}_2^T \mathbf{w}_1 - 0)$$

$\Sigma \mathbf{w}_2 = \alpha \mathbf{w}_2$ that is, \mathbf{w}_2 is another eigenvector of Σ and so on.

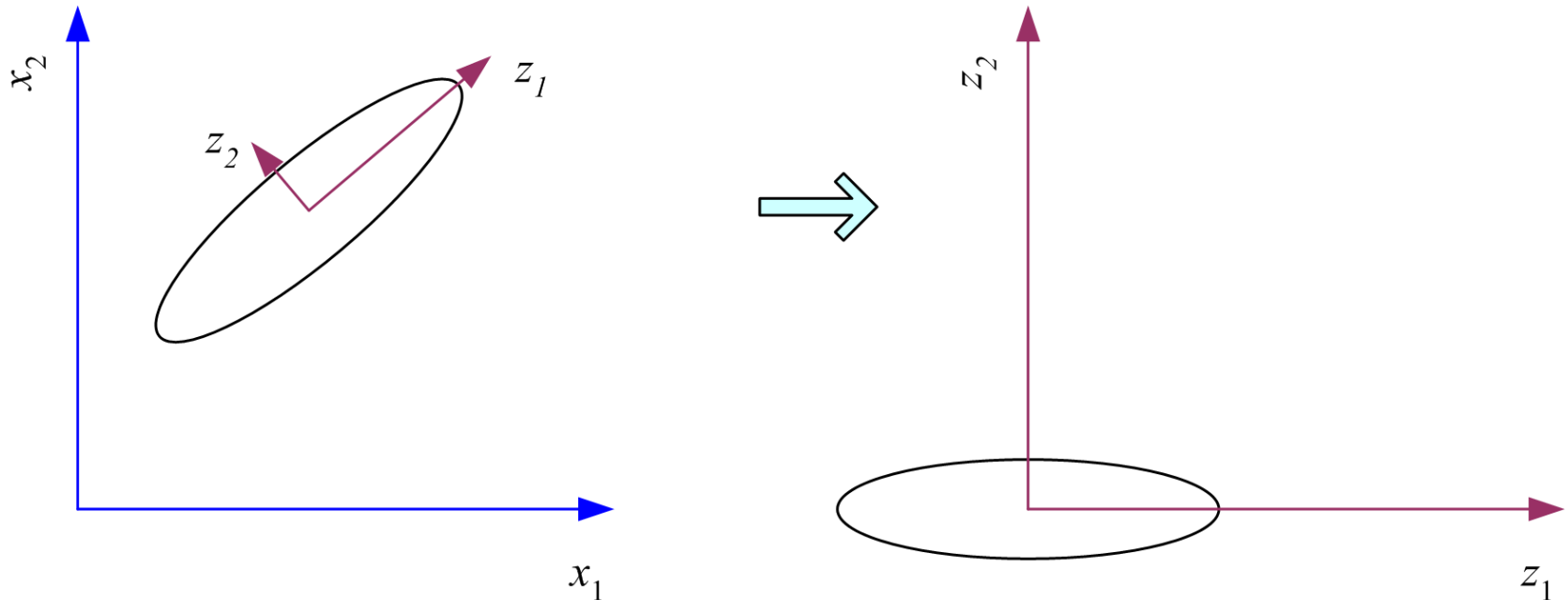
What PCA does

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$$\mathbf{z} = \mathbf{W}^T(\mathbf{x} - \mathbf{m})$$

where the columns of \mathbf{W} are the eigenvectors of Σ
and \mathbf{m} is sample mean

Centers the data at the origin and rotates the axes



How to choose k ?

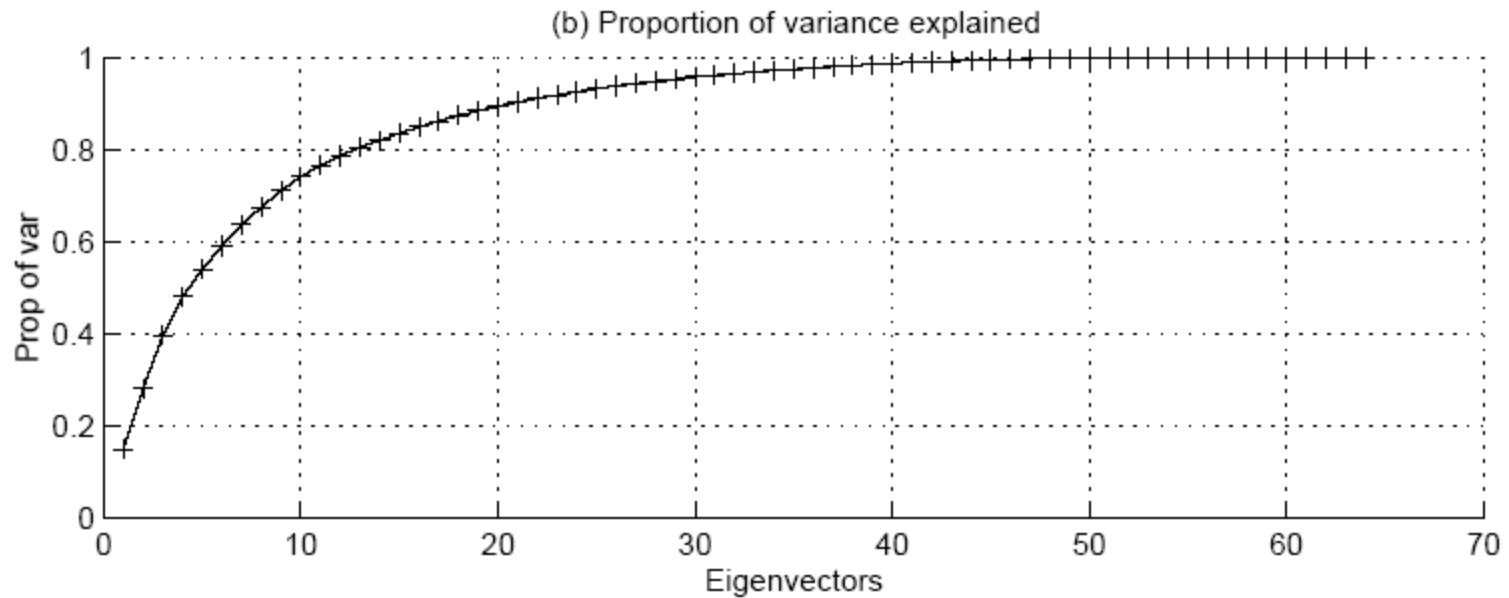
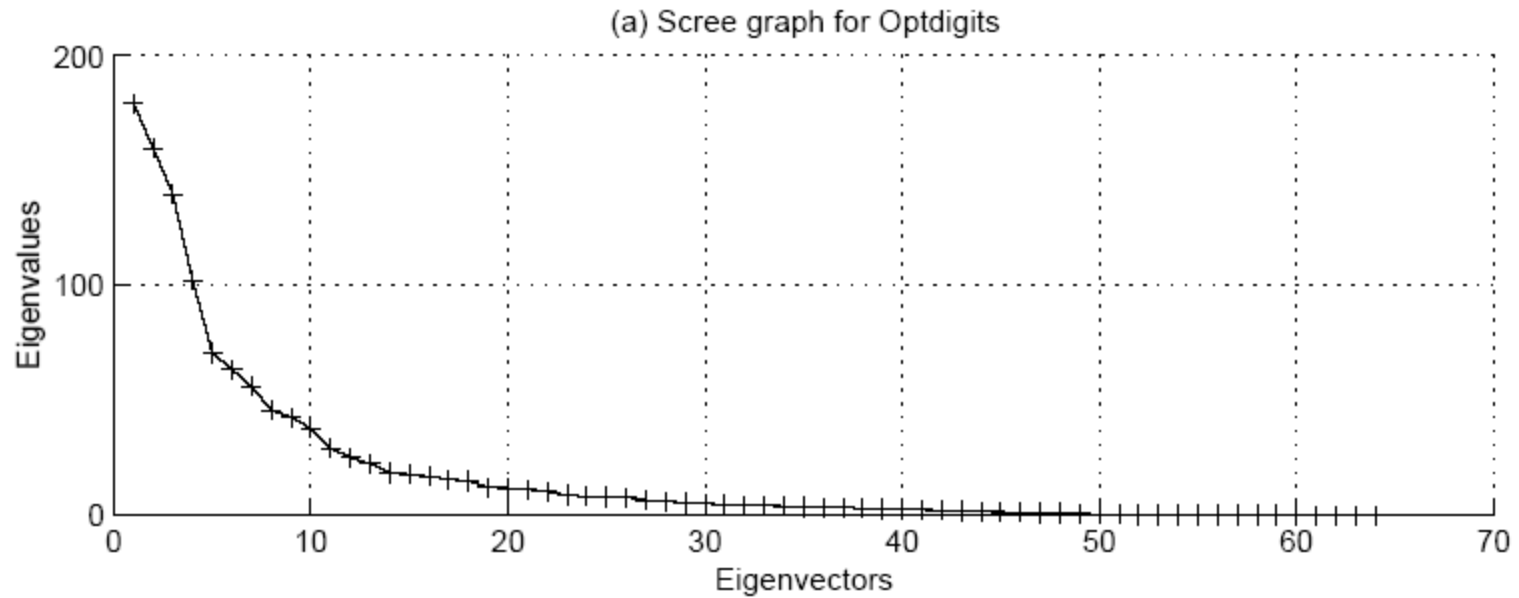
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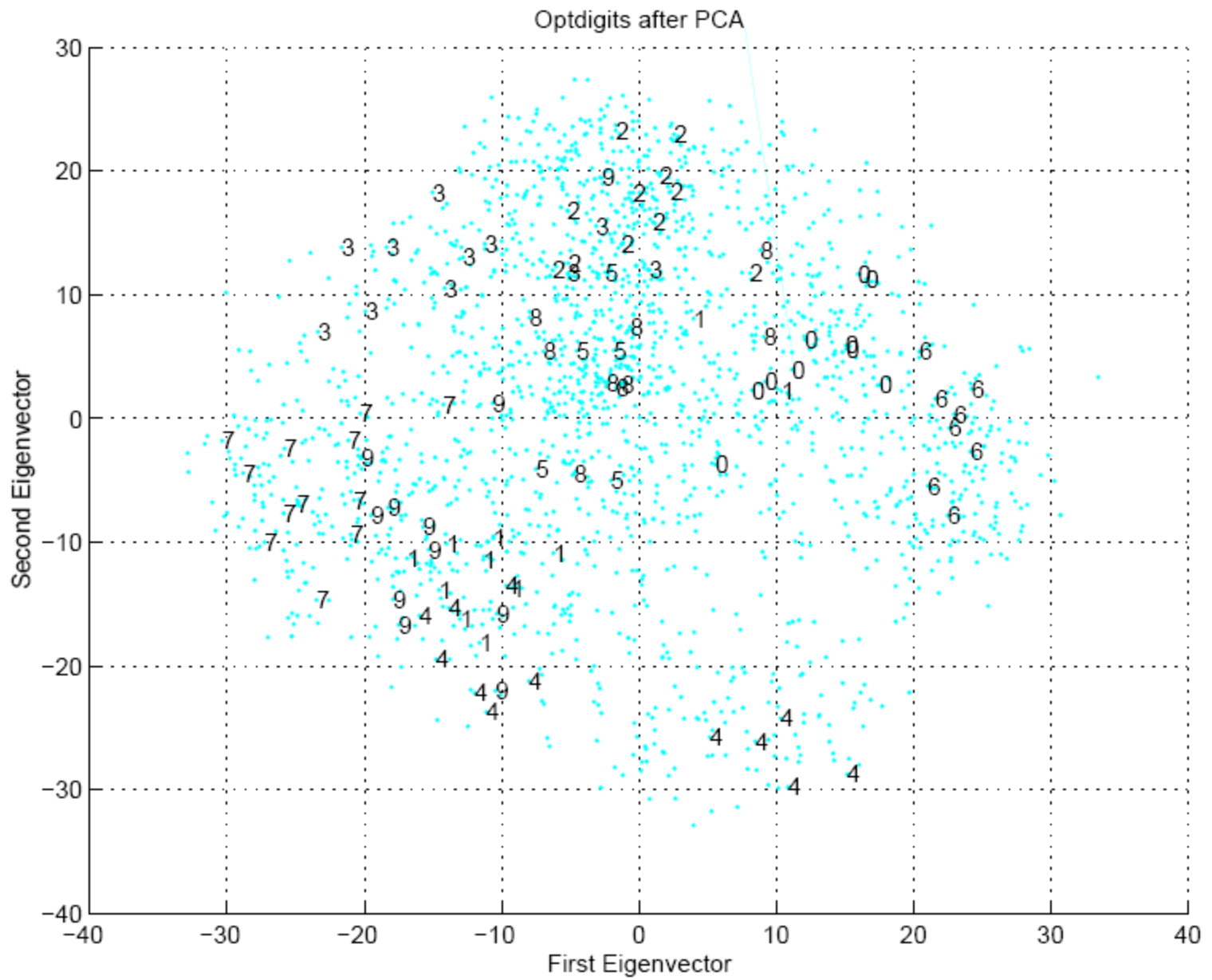
- Proportion of Variance (PoV) explained

$$\frac{\lambda_1 + \lambda_2 + \dots + \lambda_k}{\lambda_1 + \lambda_2 + \dots + \lambda_k + \dots + \lambda_d}$$

when λ_i are sorted in descending order

- Typically, stop at $\text{PoV} > 0.9$
- Scree graph plots of PoV vs k , stop at “elbow”





Feature Embedding

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- When \mathbf{X} is the $N \times d$ data matrix,
 $\mathbf{X}^T \mathbf{X}$ is the $d \times d$ matrix (covariance of features, if mean-centered)
 $\mathbf{X} \mathbf{X}^T$ is the $N \times N$ matrix (pairwise similarities of instances)
- PCA uses the eigenvectors of $\mathbf{X}^T \mathbf{X}$ which are d -dim and can be used for projection
- Feature embedding uses the eigenvectors of $\mathbf{X} \mathbf{X}^T$ which are N -dim and which give directly the coordinates after projection
- Sometimes, we can define pairwise similarities (or distances) between instances, then we can use feature embedding without needing to represent instances as vectors.

Factor Analysis

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- Find a small number of factors \mathbf{z} , which when combined generate \mathbf{x} :

$$x_i - \mu_i = v_{i1}z_1 + v_{i2}z_2 + \dots + v_{ik}z_k + \varepsilon_i$$

where $z_j, j = 1, \dots, k$ are the latent factors with

$$E[z_j] = 0, \text{Var}(z_j) = 1, \text{Cov}(z_i, z_j) = 0, i \neq j,$$

ε_i are the noise sources

$$E[\varepsilon_i] = \psi_i, \text{Cov}(\varepsilon_i, \varepsilon_j) = 0, i \neq j, \text{Cov}(\varepsilon_i, z_j) = 0,$$

and v_{ij} are the factor loadings

PCA vs FA

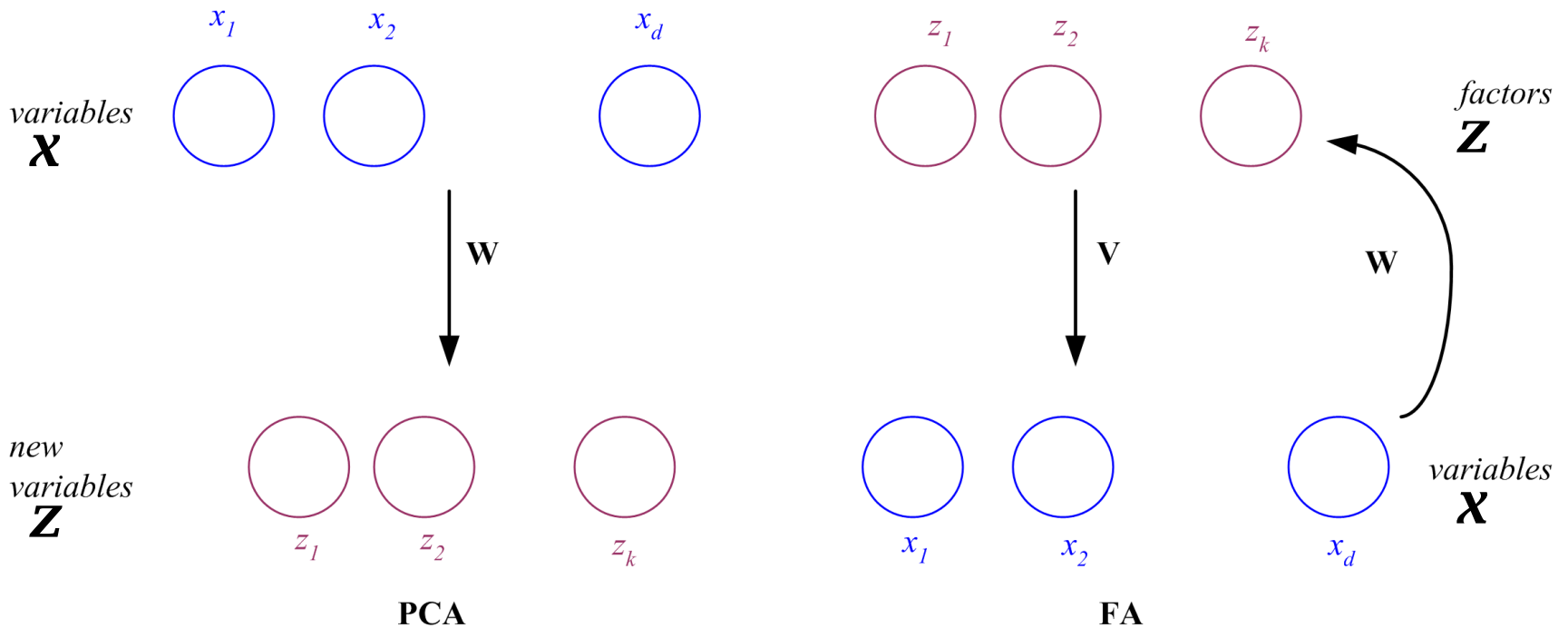
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□ PCA From \mathbf{x} to \mathbf{z}

□ FA From \mathbf{z} to \mathbf{x}

$$\mathbf{z} = \mathbf{W}^T(\mathbf{x} - \boldsymbol{\mu})$$

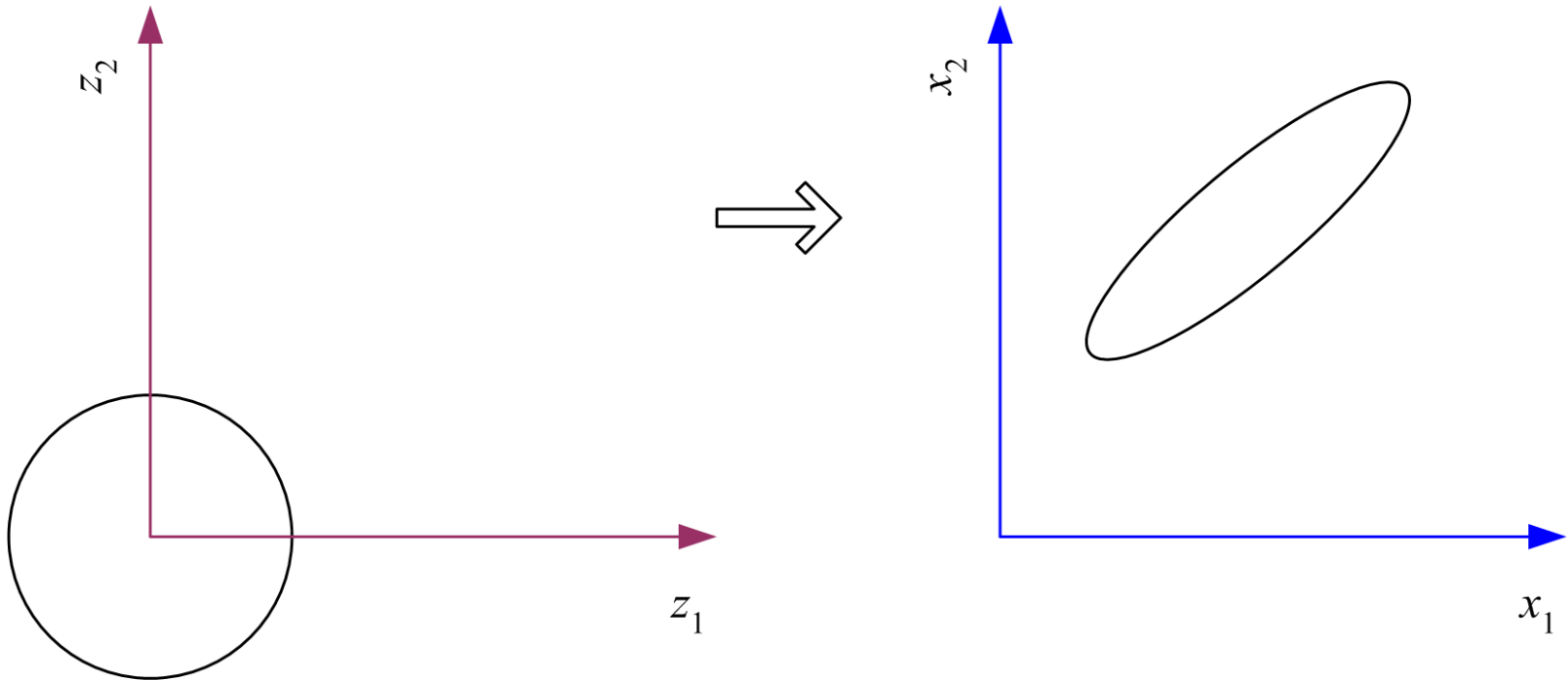
$$\mathbf{x} - \boldsymbol{\mu} = \mathbf{V}\mathbf{z} + \boldsymbol{\varepsilon}$$



Factor Analysis

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- In FA, factors z_i are stretched, rotated and translated to generate x



Singular Value Decomposition and Matrix Factorization

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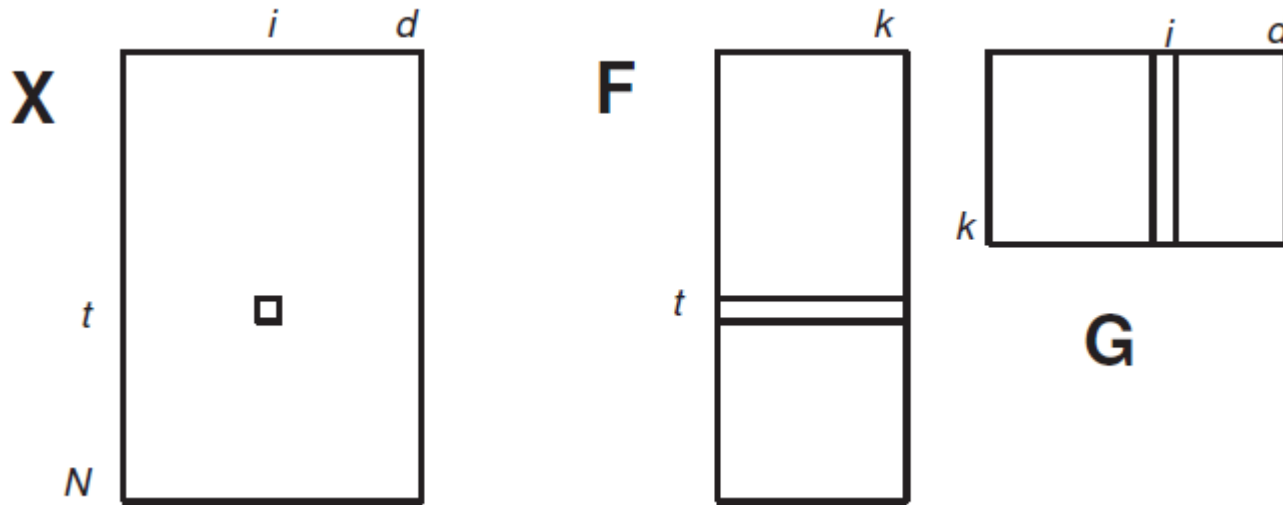
- Singular value decomposition: $\mathbf{X} = \mathbf{V}\mathbf{A}\mathbf{W}^T$
 - \mathbf{V} is $N \times N$ and contains the eigenvectors of $\mathbf{X}\mathbf{X}^T$
 - \mathbf{W} is $d \times d$ and contains the eigenvectors of $\mathbf{X}^T\mathbf{X}$
 - and \mathbf{A} is $N \times d$ and contains singular values on its first k diagonal
- $\mathbf{X} = \mathbf{u}_1 a_1 \mathbf{v}_1^T + \dots + \mathbf{u}_k a_k \mathbf{v}_k^T$ where k is the rank of \mathbf{X}

Matrix Factorization

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□ Matrix factorization: $\mathbf{X} = \mathbf{F}\mathbf{G}$

\mathbf{F} is $N \times k$ and \mathbf{G} is $k \times d$



$$X_{ti} = \mathbf{F}_t^T \mathbf{G}_i = \sum_{j=1}^k \mathbf{F}_{tj} \mathbf{G}_{ji}$$

Latent semantic indexing

Multidimensional Scaling

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- Given pairwise distances between N points,

$$d_{ij}, i, j = 1, \dots, N$$

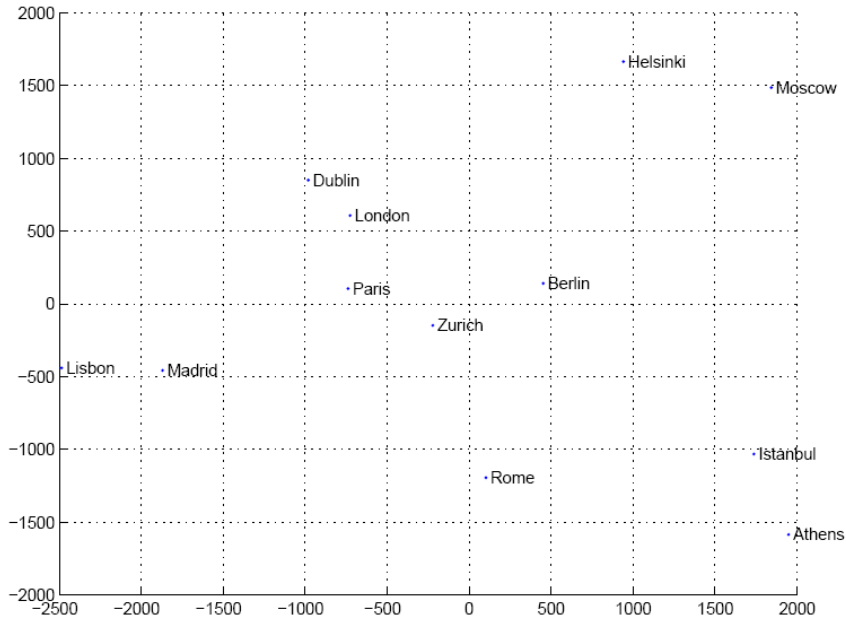
place on a low-dim map s.t. distances are preserved
(by feature embedding)

- $\mathbf{z} = \mathbf{g}(\mathbf{x} \mid \theta)$ Find θ that min Sammon stress

$$\begin{aligned} E(\theta \mid \mathcal{X}) &= \sum_{r,s} \frac{\left(\|\mathbf{z}^r - \mathbf{z}^s\| - \|\mathbf{x}^r - \mathbf{x}^s\| \right)^2}{\|\mathbf{x}^r - \mathbf{x}^s\|^2} \\ &= \sum_{r,s} \frac{\left(\|\mathbf{g}(\mathbf{x}^r \mid \theta) - \mathbf{g}(\mathbf{x}^s \mid \theta)\| - \|\mathbf{x}^r - \mathbf{x}^s\| \right)^2}{\|\mathbf{x}^r - \mathbf{x}^s\|^2} \end{aligned}$$

Map of Europe by MDS

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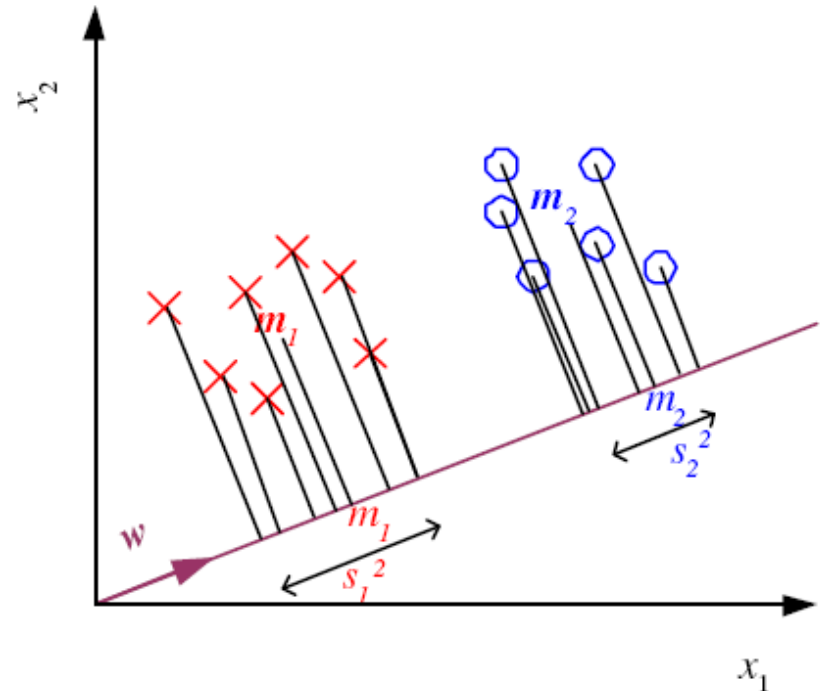
Map from CIA – The World Factbook: <http://www.cia.gov/>

Linear Discriminant Analysis

- Find a low-dimensional space such that when \mathbf{x} is projected, classes are well-separated.
- Find \mathbf{w} that maximizes

$$J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2}$$

$$m_1 = \frac{\sum_t \mathbf{w}^T \mathbf{x}^t r^t}{\sum_t r^t} \quad s_1^2 = \sum_t (\mathbf{w}^T \mathbf{x}^t - m_1)^2 r^t$$



□ Between-class scatter:

$$\begin{aligned}(m_1 - m_2)^2 &= (\mathbf{w}^T \mathbf{m}_1 - \mathbf{w}^T \mathbf{m}_2)^2 \\ &= \mathbf{w}^T (\mathbf{m}_1 - \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2)^T \mathbf{w} \\ &= \mathbf{w}^T \mathbf{S}_B \mathbf{w} \text{ where } \mathbf{S}_B = (\mathbf{m}_1 - \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2)^T\end{aligned}$$

□ Within-class scatter:

$$\begin{aligned}s_1^2 &= \sum_t (\mathbf{w}^T \mathbf{x}^t - m_1)^2 r^t \\ &= \sum_t \mathbf{w}^T (\mathbf{x}^t - \mathbf{m}_1) (\mathbf{x}^t - \mathbf{m}_1)^T \mathbf{w} r^t = \mathbf{w}^T \mathbf{S}_1 \mathbf{w}\end{aligned}$$

where $\mathbf{S}_1 = \sum_t (\mathbf{x}^t - \mathbf{m}_1) (\mathbf{x}^t - \mathbf{m}_1)^T r^t$

$$s_1^2 + s_2^2 = \mathbf{w}^T \mathbf{S}_W \mathbf{w} \text{ where } \mathbf{S}_W = \mathbf{S}_1 + \mathbf{S}_2$$

Fisher's Linear Discriminant

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- Find \mathbf{w} that max

$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}} = \frac{|\mathbf{w}^T (\mathbf{m}_1 - \mathbf{m}_2)|^2}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

- LDA soln:

$$\mathbf{w} = c \cdot \mathbf{S}_W^{-1} (\mathbf{m}_1 - \mathbf{m}_2)$$

- Parametric soln:

$$\mathbf{w} = \Sigma^{-1} (\mu_1 - \mu_2)$$

$$\text{when } p(\mathbf{x} | C_i) \sim \mathcal{N}(\mu_i, \Sigma)$$

K > 2 Classes

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- Within-class scatter:

$$\mathbf{S}_W = \sum_{i=1}^K \mathbf{S}_i \quad \mathbf{S}_i = \sum_t r_i^t (\mathbf{x}^t - \mathbf{m}_i)(\mathbf{x}^t - \mathbf{m}_i)^T$$

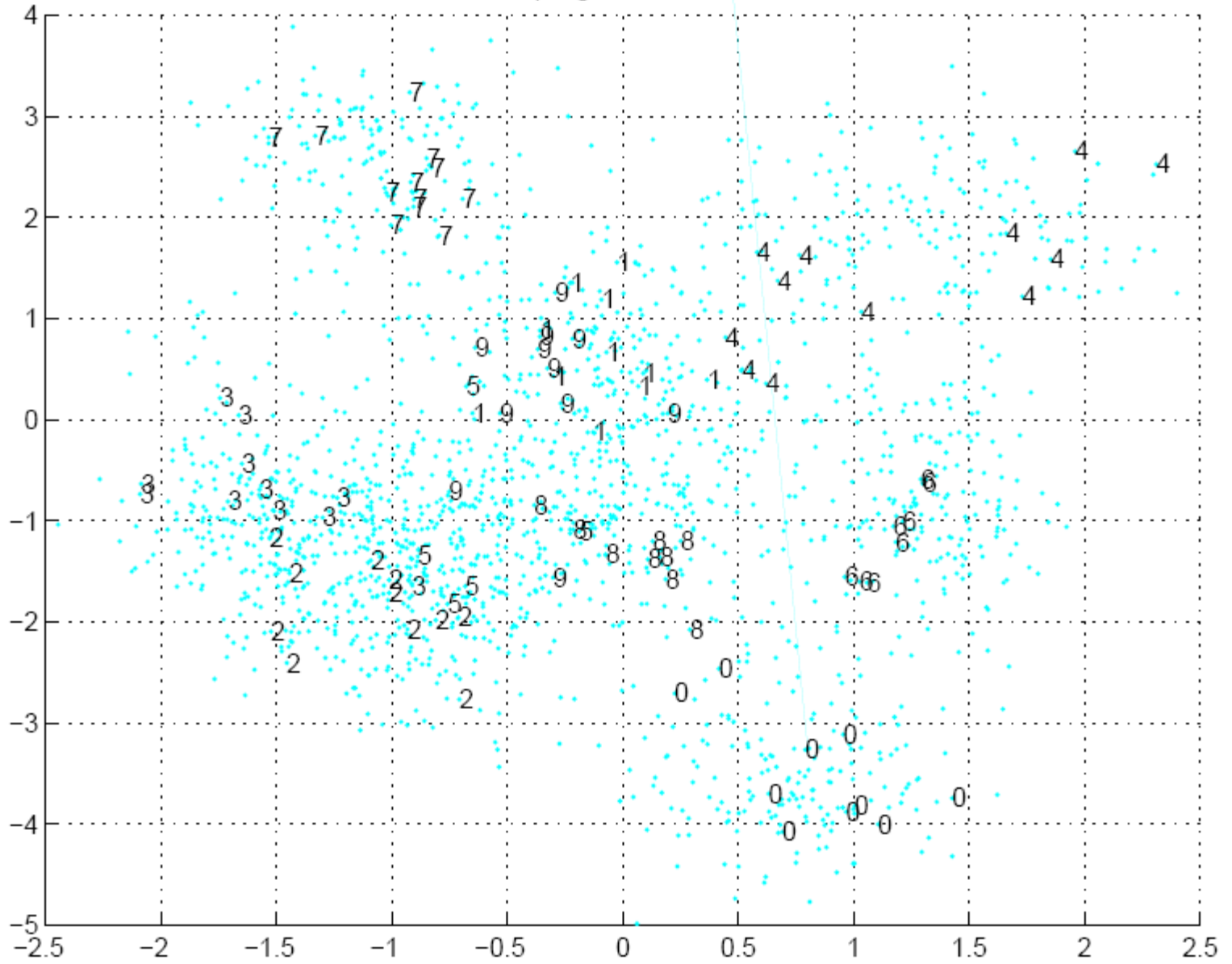
- Between-class scatter:

$$\mathbf{S}_B = \sum_{i=1}^K N_i (\mathbf{m}_i - \mathbf{m})(\mathbf{m}_i - \mathbf{m})^T \quad \mathbf{m} = \frac{1}{K} \sum_{i=1}^K \mathbf{m}_i$$

- Find \mathbf{W} that max $J(\mathbf{W}) = \frac{|\mathbf{W}^T \mathbf{S}_B \mathbf{W}|}{|\mathbf{W}^T \mathbf{S}_W \mathbf{W}|}$

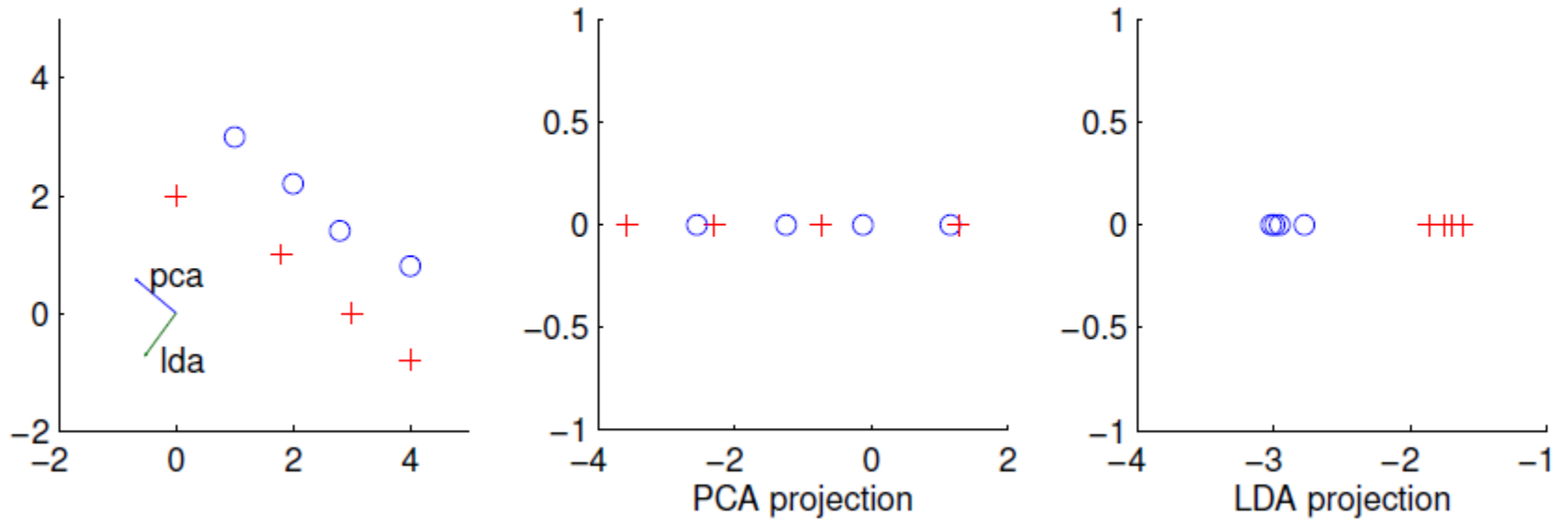
The largest eigenvectors of $\mathbf{S}_W^{-1} \mathbf{S}_B$, maximum rank of $K-1$

Optdigits after LDA



PCA vs LDA

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Canonical Correlation Analysis

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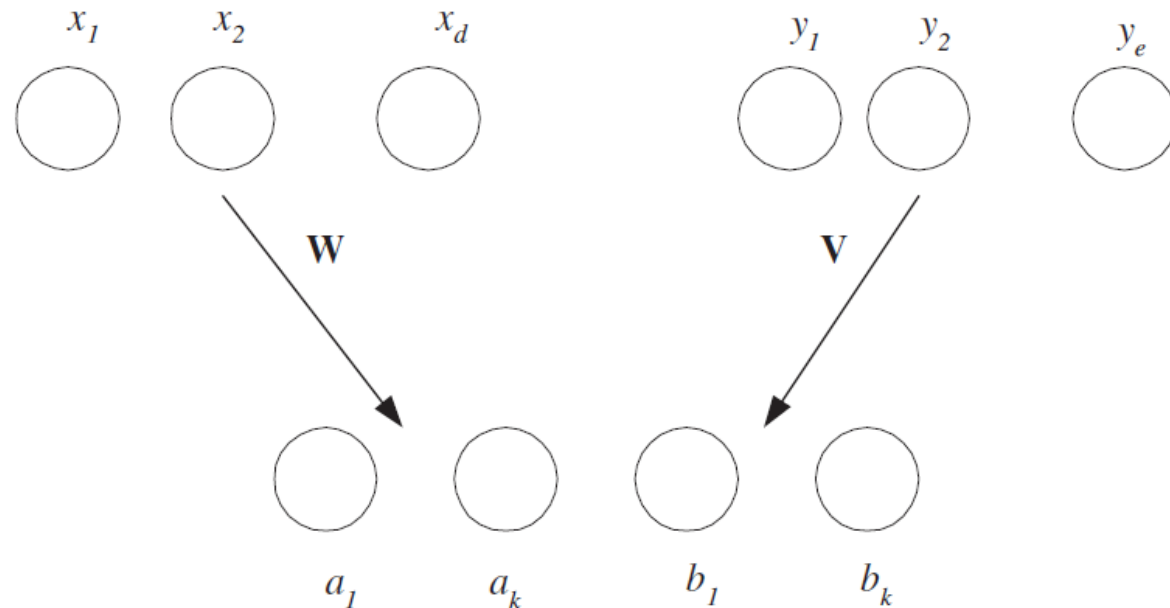
- $\mathbf{X} = \{\mathbf{x}^t, \mathbf{y}^t\}_t$; two sets of variables \mathbf{x} and \mathbf{y}
- We want to find two projections \mathbf{w} and \mathbf{v} st when \mathbf{x} is projected along \mathbf{w} and \mathbf{y} is projected along \mathbf{v} , the correlation is maximized:

$$\begin{aligned}\rho &= \text{Corr}(\mathbf{w}^T \mathbf{x}, \mathbf{v}^T \mathbf{y}) = \frac{\text{Cov}(\mathbf{w}^T \mathbf{x}, \mathbf{v}^T \mathbf{y})}{\sqrt{\text{Var}(\mathbf{w}^T \mathbf{x})} \sqrt{\text{Var}(\mathbf{v}^T \mathbf{y})}} \\ &= \frac{\mathbf{w}^T \text{Cov}(\mathbf{x}, \mathbf{y}) \mathbf{v}}{\sqrt{\mathbf{w}^T \text{Var}(\mathbf{x}) \mathbf{w}} \sqrt{\mathbf{v}^T \text{Var}(\mathbf{y}) \mathbf{v}}} = \frac{\mathbf{w}^T \mathbf{S}_{xy} \mathbf{v}}{\sqrt{\mathbf{w}^T \mathbf{S}_{xx} \mathbf{w}} \sqrt{\mathbf{v}^T \mathbf{S}_{yy} \mathbf{v}}}\end{aligned}$$

CCA

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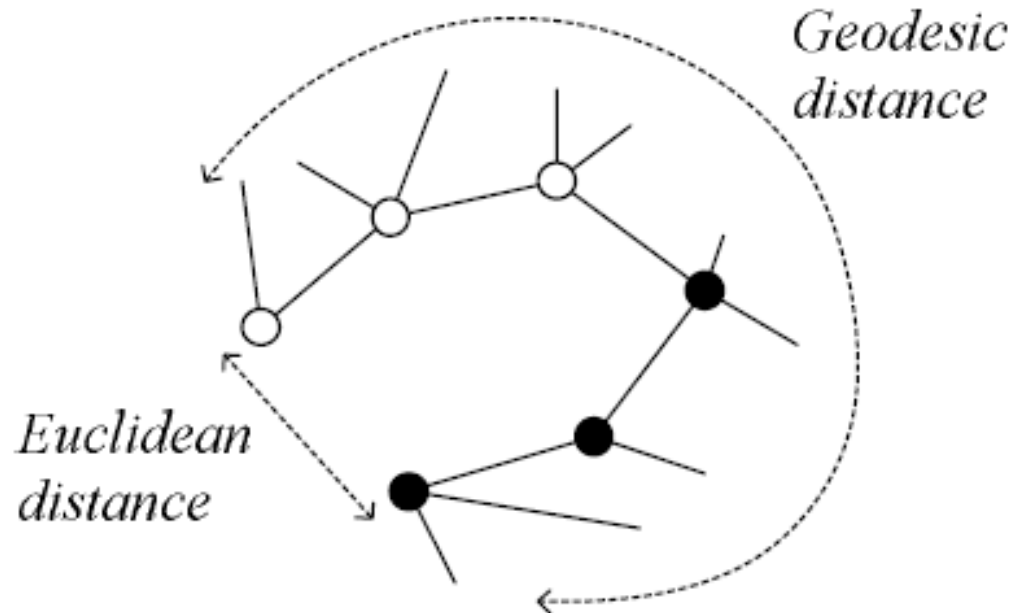
- x and y may be two different views or modalities; e.g., image and word tags, and CCA does a joint mapping



Isomap

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- Geodesic distance is the distance along the manifold that the data lies in, as opposed to the Euclidean distance in the input space

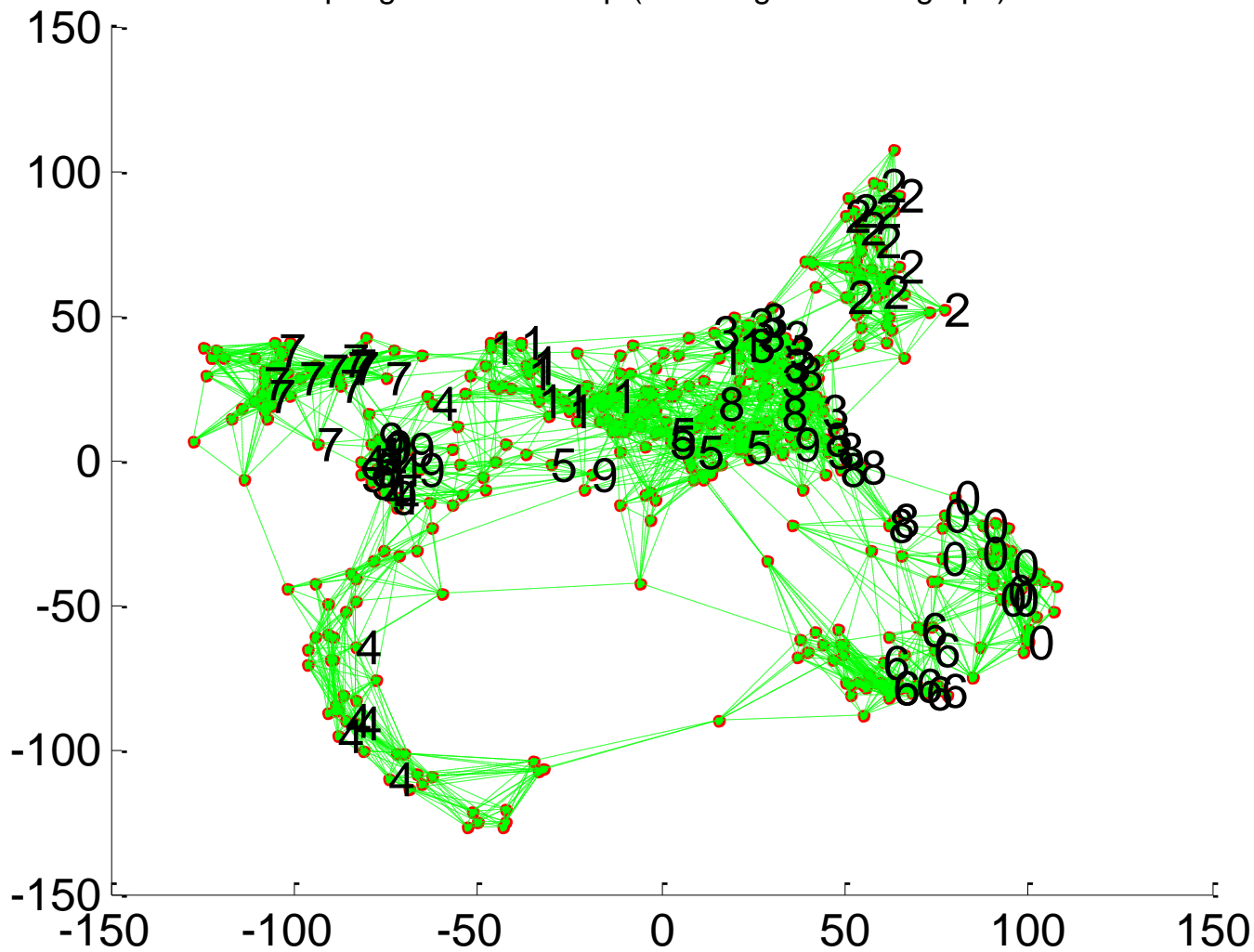


Isomap

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- Instances r and s are connected in the graph if $\| \mathbf{x}^r - \mathbf{x}^s \| < \varepsilon$ or if \mathbf{x}^s is one of the k neighbors of \mathbf{x}^r
The edge length is $\| \mathbf{x}^r - \mathbf{x}^s \|$
- For two nodes r and s not connected, the distance is equal to the shortest path between them
- Once the $N \times N$ distance matrix is thus formed, use MDS to find a lower-dimensional mapping

Optdigits after Isomap (with neighborhood graph).



Matlab source from <http://web.mit.edu/cocosci/isomap/isomap.html>

Locally Linear Embedding

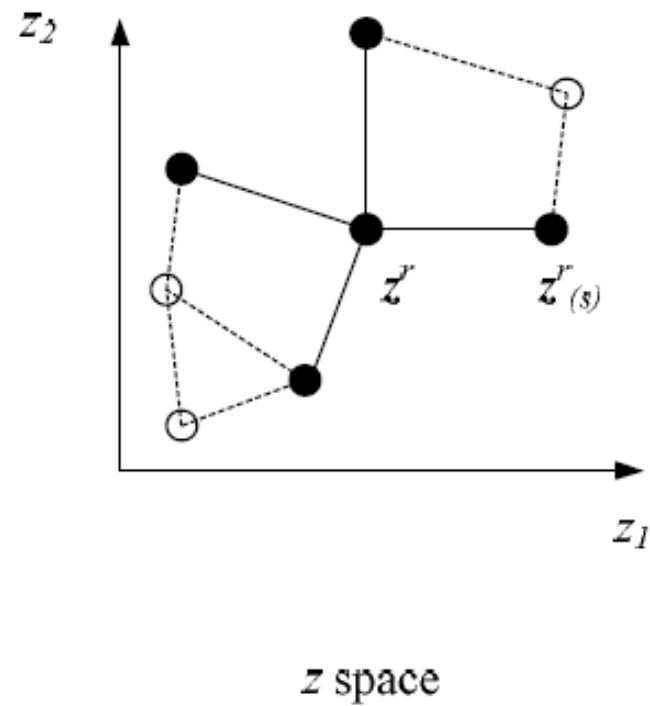
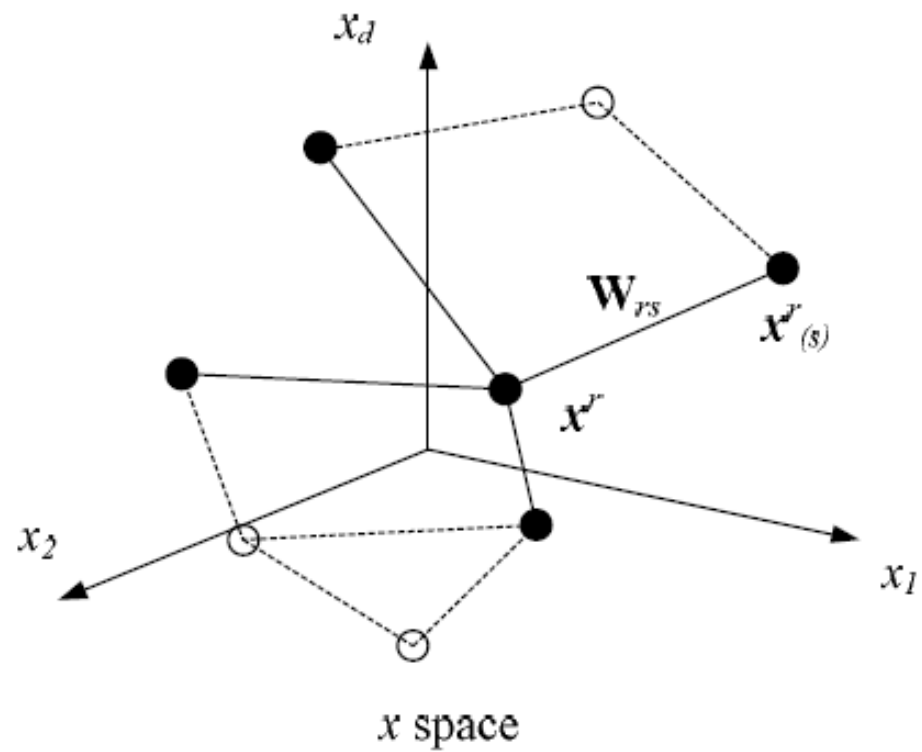
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1. Given \mathbf{x}^r find its neighbors $\mathbf{x}_{(r)}^s$
2. Find \mathbf{W}_{rs} that minimize

$$E(\mathbf{W} | X) = \sum_r \left\| \mathbf{x}^r - \sum_s \mathbf{W}_{rs} \mathbf{x}_{(r)}^s \right\|^2$$

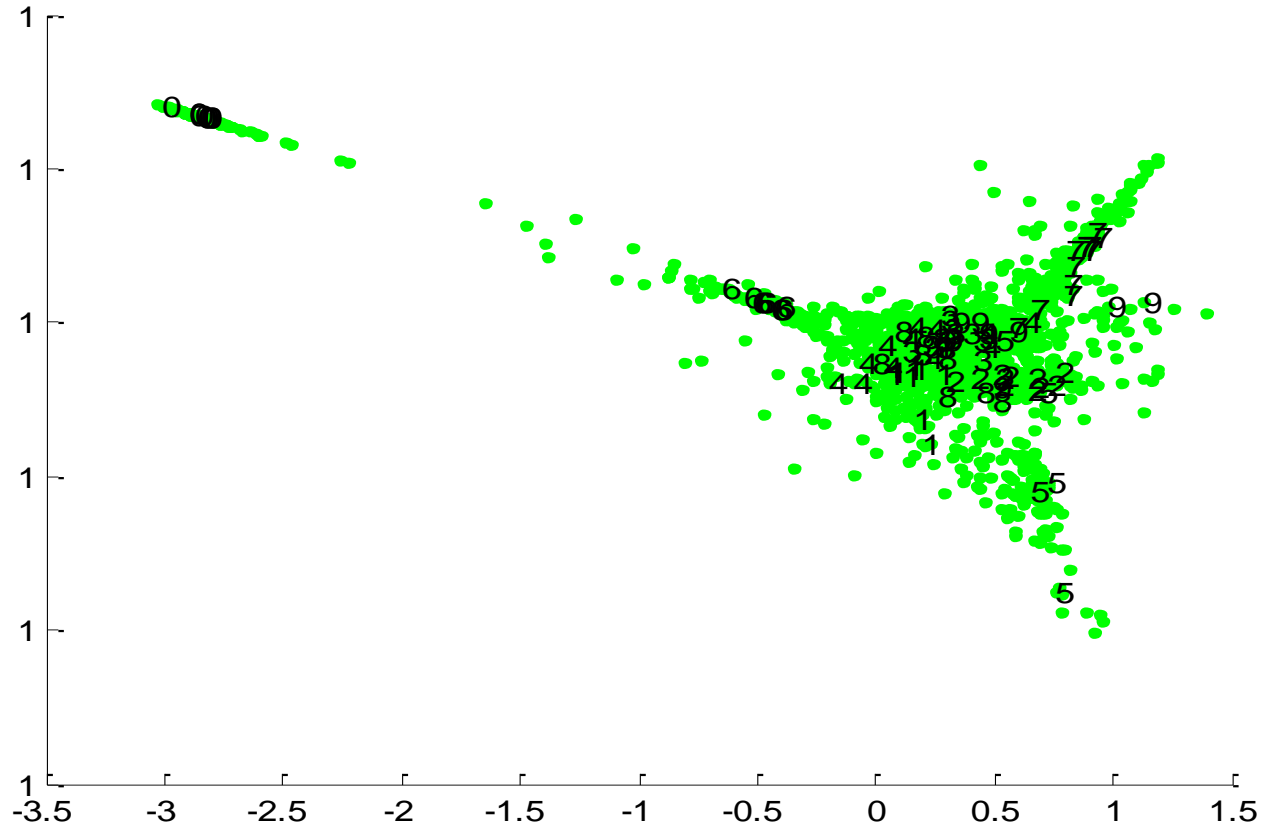
3. Find the new coordinates \mathbf{z}^r that minimize

$$E(\mathbf{z} | \mathbf{W}) = \sum_r \left\| \mathbf{z}^r - \sum_s \mathbf{W}_{rs} \mathbf{z}_{(r)}^s \right\|^2$$



LLE on Optdigits

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Matlab source from <http://www.cs.toronto.edu/~roweis/lle/code.html>

Laplacian Eigenmaps

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- Let r and s be two instances and B_{rs} is their similarity, we want to find \mathbf{z}^r and \mathbf{z}^s that

$$\min \sum_{r,s} \|\mathbf{z}^r - \mathbf{z}^s\|^2 B_{rs}$$

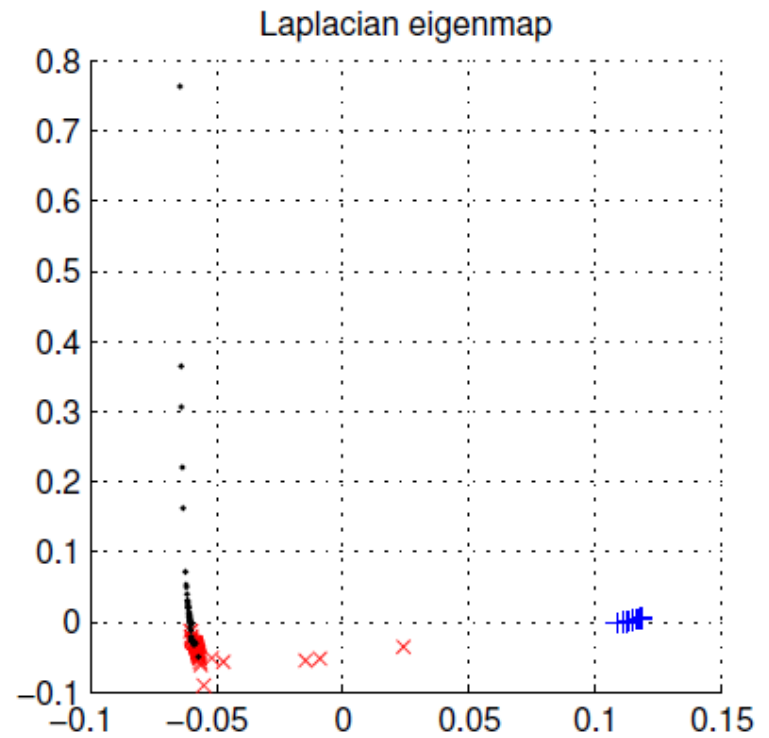
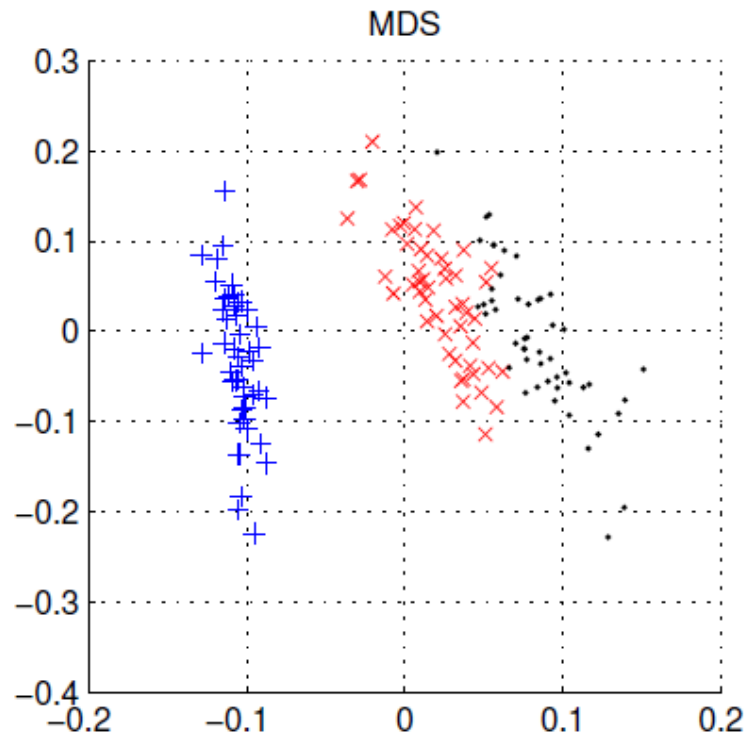
- B_{rs} can be defined in terms of similarity in an original space: 0 if \mathbf{x}^r and \mathbf{x}^s are too far, otherwise

$$B_{rs} = \exp \left[-\frac{\|\mathbf{x}^r - \mathbf{x}^s\|^2}{2\sigma^2} \right]$$

- Defines a graph Laplacian, and feature embedding returns \mathbf{z}^r

Laplacian Eigenmaps on Iris

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Spectral clustering (chapter 7)