

Lecture Slides for

INTRODUCTION TO

Machine Learning

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CHAPTER 3:

Bayesian Decision Theory



Probability and Inference

- Result of tossing a coin is $\in \{\text{Heads}, \text{Tails}\}$
- Random var $X \in \{1, 0\}$

Bernoulli: $P\{X=1\} = p_o^X (1 - p_o)^{1-X}$

- Sample: $X = \{x^t\}_{t=1}^N$
Estimation: $p_o = \# \{\text{Heads}\} / \# \{\text{Tosses}\} = \sum_t x^t / N$
- Prediction of next toss:
Heads if $p_o > \frac{1}{2}$, Tails otherwise



Classification

- Credit scoring: Inputs are income and savings.
Output is low-risk vs high-risk
- Input: $\mathbf{x} = [x_1, x_2]^T$, Output: $C \in \{0,1\}$
- Prediction:
$$\text{choose } \begin{cases} C = 1 \text{ if } P(C = 1 | x_1, x_2) > 0.5 \\ C = 0 \text{ otherwise} \end{cases}$$

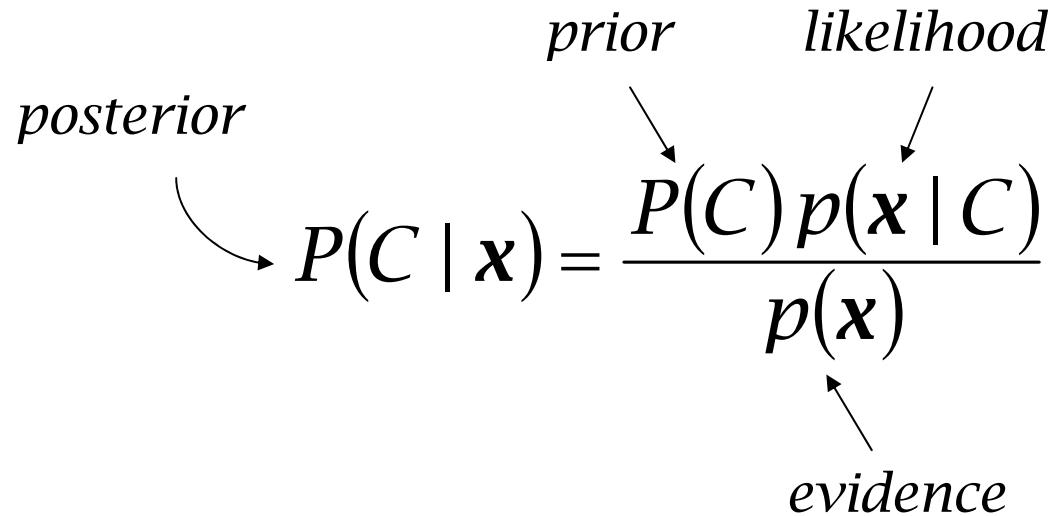
or equivalently
$$\text{choose } \begin{cases} C = 1 \text{ if } P(C = 1 | x_1, x_2) > P(C = 0 | x_1, x_2) \\ C = 0 \text{ otherwise} \end{cases}$$



Bayes' Rule

$$P(C | \mathbf{x}) = \frac{P(C) p(\mathbf{x} | C)}{p(\mathbf{x})}$$

prior *likelihood*
posterior *evidence*



$$P(C = 0) + P(C = 1) = 1$$

$$p(\mathbf{x}) = p(\mathbf{x} | C = 1)P(C = 1) + p(\mathbf{x} | C = 0)P(C = 0)$$

$$p(C = 0 | \mathbf{x}) + P(C = 1 | \mathbf{x}) = 1$$



Bayes' Rule: $K > 2$ Classes

$$\begin{aligned} P(C_i | \mathbf{x}) &= \frac{p(\mathbf{x} | C_i)P(C_i)}{p(\mathbf{x})} \\ &= \frac{p(\mathbf{x} | C_i)P(C_i)}{\sum_{k=1}^K p(\mathbf{x} | C_k)P(C_k)} \end{aligned}$$

$$P(C_i) \geq 0 \text{ and } \sum_{i=1}^K P(C_i) = 1$$

choose C_i if $P(C_i | \mathbf{x}) = \max_k P(C_k | \mathbf{x})$



Losses and Risks

- Actions: α_i
- Loss of α_i when the state is C_k : λ_{ik}
- Expected risk (Duda and Hart, 1973)

$$R(\alpha_i \mid \mathbf{x}) = \sum_{k=1}^K \lambda_{ik} P(C_k \mid \mathbf{x})$$

choose α_i if $R(\alpha_i \mid \mathbf{x}) = \min_k R(\alpha_k \mid \mathbf{x})$

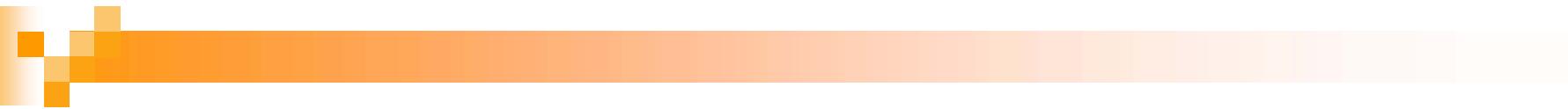


Losses and Risks: 0/1 Loss

$$\lambda_{ik} = \begin{cases} 0 & \text{if } i = k \\ 1 & \text{if } i \neq k \end{cases}$$

$$\begin{aligned} R(\alpha_i \mid \mathbf{x}) &= \sum_{k=1}^K \lambda_{ik} P(C_k \mid \mathbf{x}) \\ &= \sum_{k \neq i} P(C_k \mid \mathbf{x}) \\ &= 1 - P(C_i \mid \mathbf{x}) \end{aligned}$$

For minimum risk, choose the most probable class



Losses and Risks: Reject

$$\lambda_{ik} = \begin{cases} 0 & \text{if } i = k \\ \lambda & \text{if } i = K + 1, \quad 0 < \lambda < 1 \\ 1 & \text{otherwise} \end{cases}$$

$$R(\alpha_{K+1} | \mathbf{x}) = \sum_{k=1}^K \lambda P(C_k | \mathbf{x}) = \lambda$$

$$R(\alpha_i | \mathbf{x}) = \sum_{k \neq i} P(C_k | \mathbf{x}) = 1 - P(C_i | \mathbf{x})$$

choose C_i if $P(C_i | \mathbf{x}) > P(C_k | \mathbf{x}) \ \forall k \neq i$ and $P(C_i | \mathbf{x}) > 1 - \lambda$
reject otherwise



Discriminant Functions

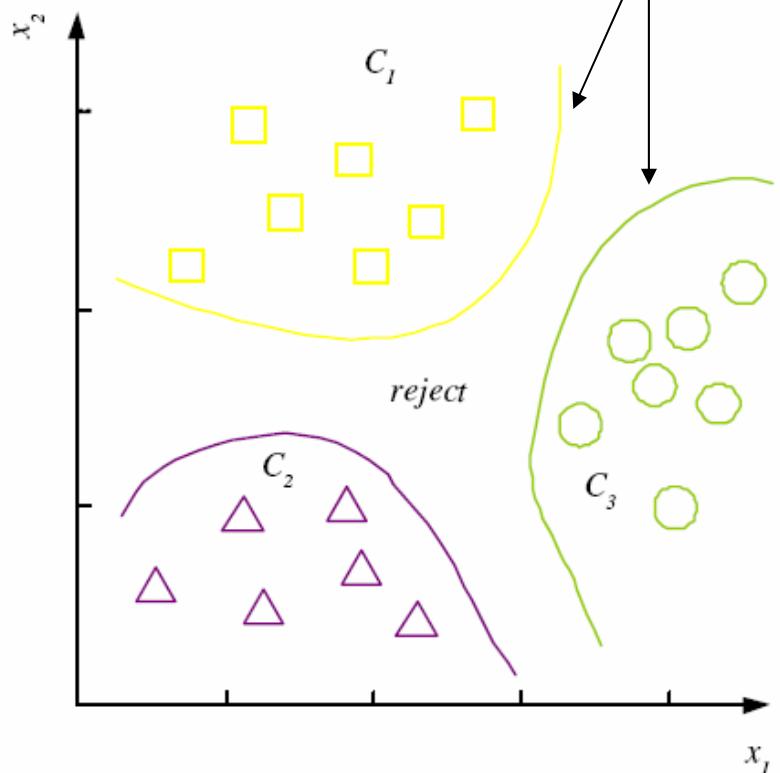
choose C_i if $g_i(\mathbf{x}) = \max_k g_k(\mathbf{x})$

$$g_i(\mathbf{x}) = \begin{cases} -R(\alpha_i | \mathbf{x}) \\ P(C_i | \mathbf{x}) \\ p(\mathbf{x} | C_i)P(C_i) \end{cases}$$

K decision regions $\mathcal{R}_1, \dots, \mathcal{R}_K$

$$\mathcal{R}_i = \{\mathbf{x} \mid g_i(\mathbf{x}) = \max_k g_k(\mathbf{x})\}$$

$g_i(\mathbf{x}), i = 1, \dots, K$





K=2 Classes

- Dichotomizer ($K=2$) vs Polychotomizer ($K>2$)
- $g(\mathbf{x}) = g_1(\mathbf{x}) - g_2(\mathbf{x})$

choose $\begin{cases} C_1 & \text{if } g(\mathbf{x}) > 0 \\ C_2 & \text{otherwise} \end{cases}$

- *Log odds:*

$$\log \frac{P(C_1 | \mathbf{x})}{P(C_2 | \mathbf{x})}$$



Utility Theory

- Prob of state k given evidence \mathbf{x} : $P(S_k|\mathbf{x})$
- Utility of a_i when state is k : U_{ik}
- Expected utility:

$$EU(\alpha_i | \mathbf{x}) = \sum_k U_{ik} P(S_k | \mathbf{x})$$

Choose α_i if $EU(\alpha_i | \mathbf{x}) = \max_j EU(\alpha_j | \mathbf{x})$



Value of Information

- Expected utility using x only

$$EU(x) = \max_i \sum_k U_{ik} P(S_k | x)$$

- Expected utility using x and new feature z

$$EU(x, z) = \max_i \sum_k U_{ik} P(S_k | x, z)$$

- z is useful if $EU(x, z) > EU(x)$

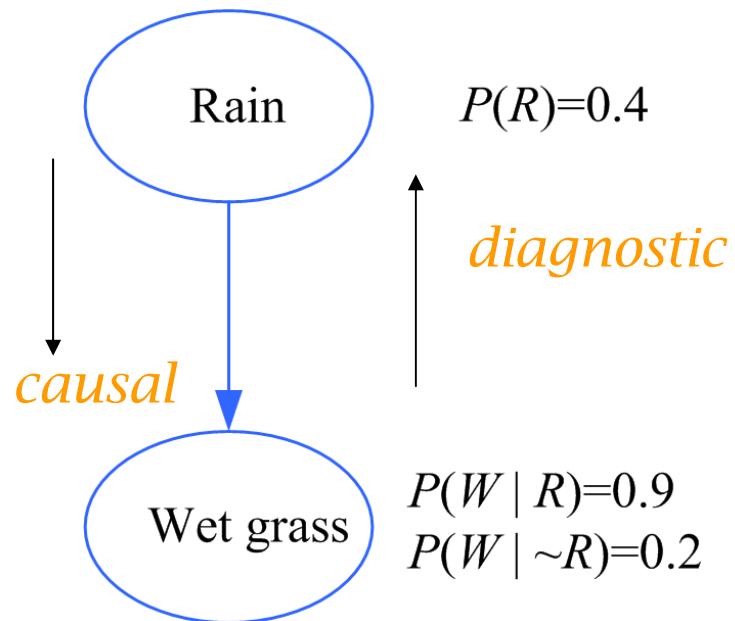


Bayesian Networks

- Aka graphical models, probabilistic networks
- Nodes are hypotheses (random vars) and the prob corresponds to our belief in the truth of the hypothesis
- Arcs are direct influences between hypotheses
- The structure is represented as a directed acyclic graph (DAG)
- The parameters are the conditional probs in the arcs
- (Pearl, 1988, 2000; Jensen, 1996; Lauritzen, 1996)

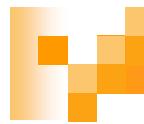


Causes and Bayes' Rule



Diagnostic inference:
Knowing that the grass is wet,
what is the probability that rain is
the cause?

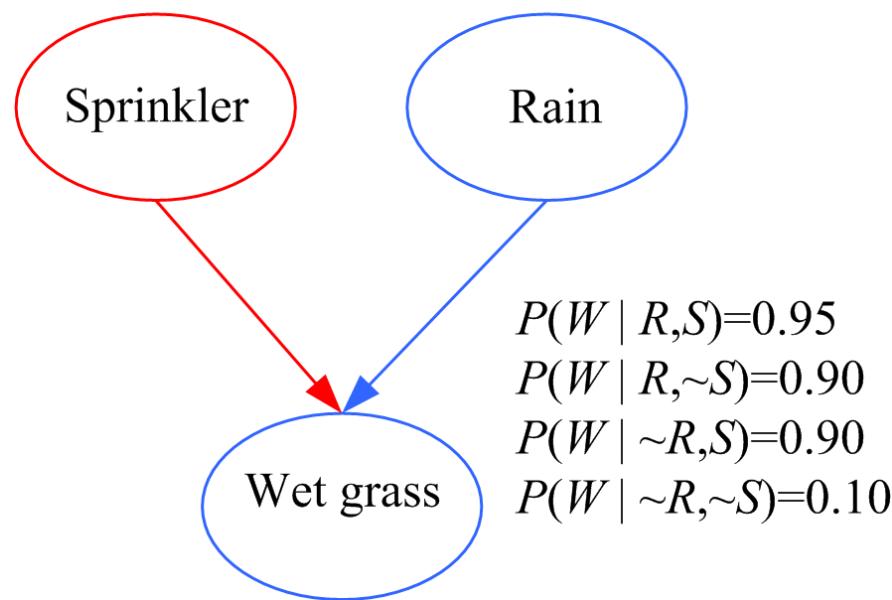
$$\begin{aligned}P(R | W) &= \frac{P(W | R)P(R)}{P(W)} \\&= \frac{P(W | R)P(R)}{P(W | R)P(R) + P(W | \sim R)P(\sim R)} \\&= \frac{0.9 \times 0.4}{0.9 \times 0.4 + 0.2 \times 0.6} = 0.75\end{aligned}$$



Causal vs Diagnostic Inference

$$P(S)=0.2$$

$$P(R)=0.4$$



Causal inference: If the sprinkler is on, what is the probability that the grass is wet?

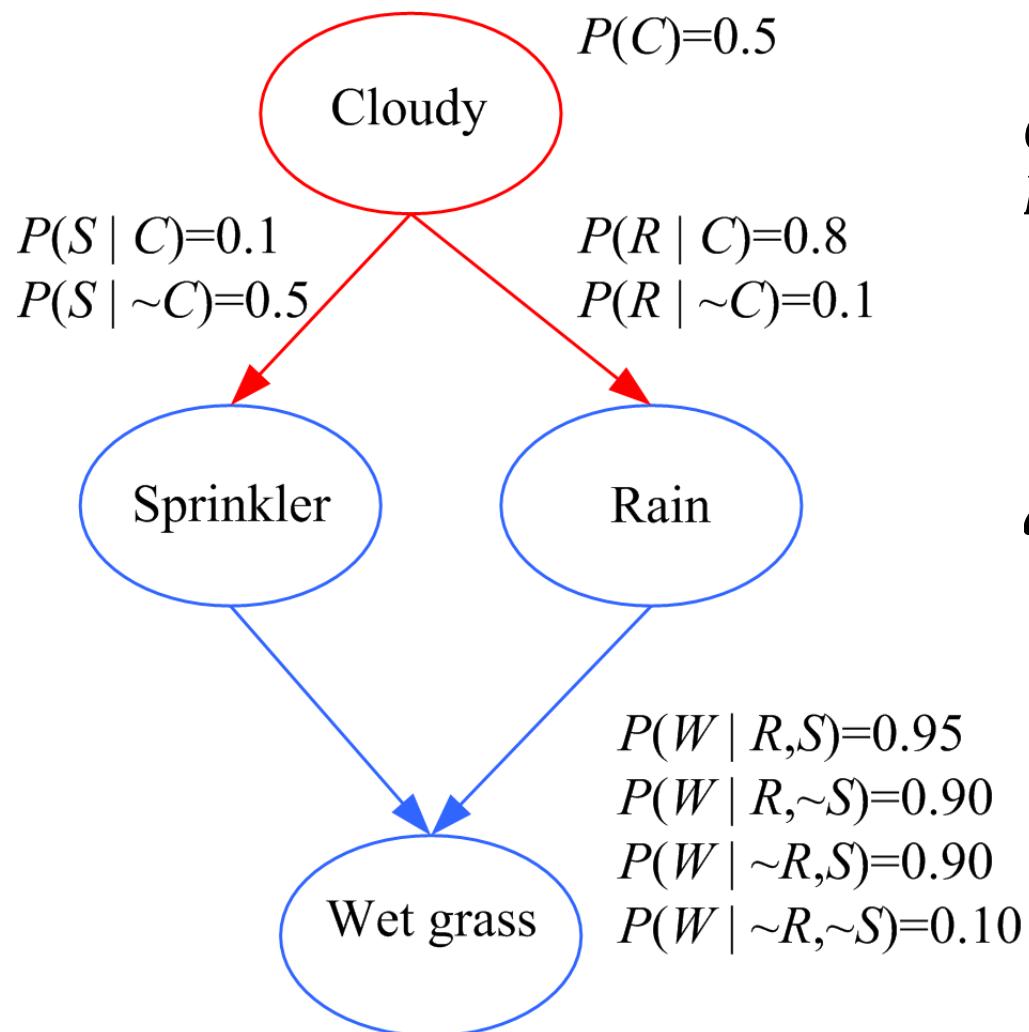
$$\begin{aligned} P(W|S) &= P(W|R,S) P(R|S) + \\ &\quad P(W|\sim R,S) P(\sim R|S) \\ &= P(W|R,S) P(R) + \\ &\quad P(W|\sim R,S) P(\sim R) \\ &= 0.95 \cdot 0.4 + 0.9 \cdot 0.6 = 0.92 \end{aligned}$$

Diagnostic inference: If the grass is wet, what is the probability that the sprinkler is on? $P(S|W) = 0.35 > 0.2 = P(S)$

$P(S|R,W) = 0.21$ *Explaining away:* Knowing that it has rained decreases the probability that the sprinkler is on.



Bayesian Networks: Causes



Causal inference:

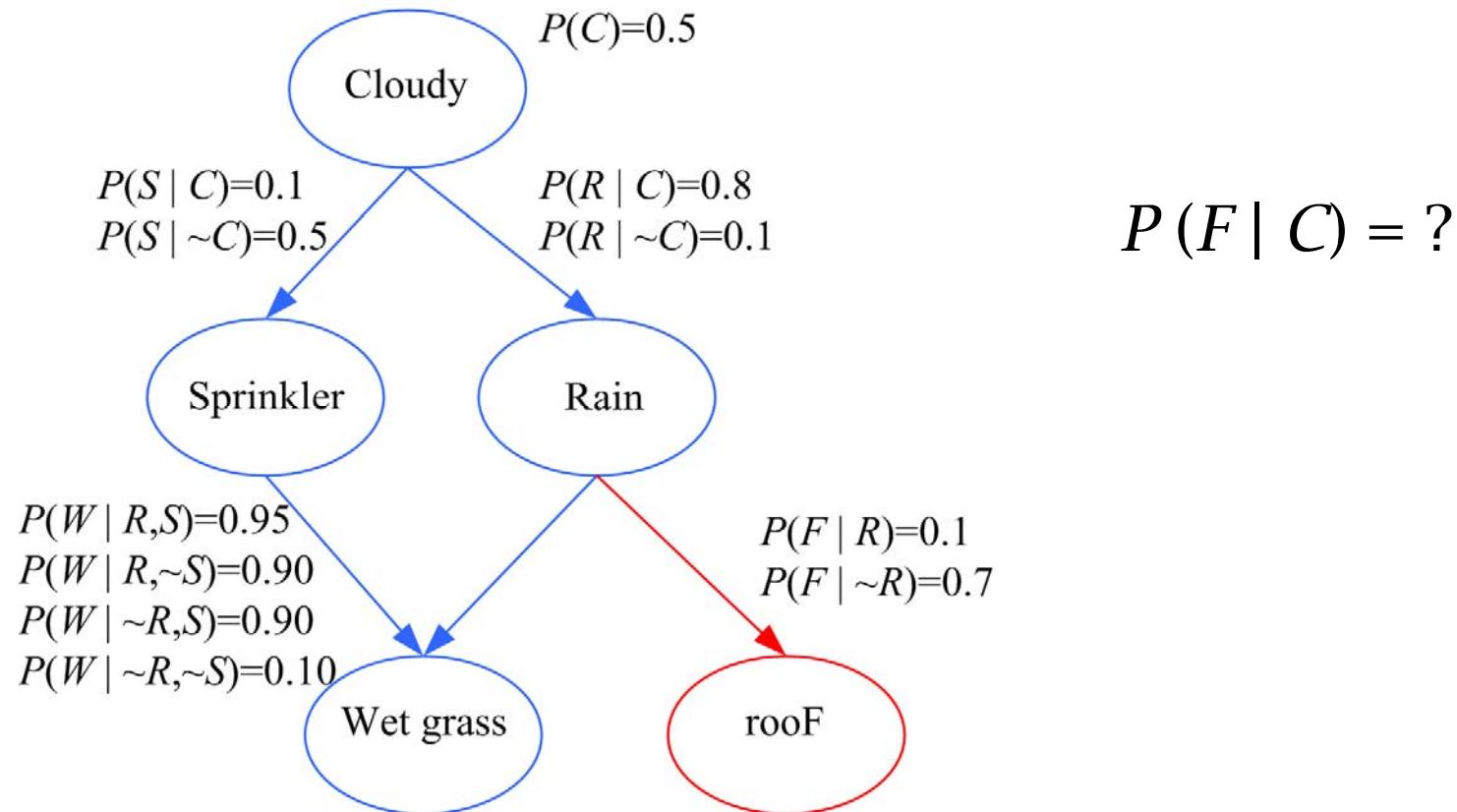
$$P(W|C) = P(W|R,S) P(R,S|C) + P(W|\sim R,S) P(\sim R,S|C) + P(W|R,\sim S) P(R,\sim S|C) + P(W|\sim R,\sim S) P(\sim R,\sim S|C)$$

and use the fact that
 $P(R,S|C) = P(R|C) P(S|C)$

Diagnostic: $P(C|W) = ?$



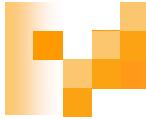
Bayesian Nets: Local structure



$$P(C, S, R, W, F) = P(C) \prod_{i=1}^d P(X_i | \text{parents}(X_i))$$

$$P(X_1, \dots, X_d) = \prod_{i=1}^d P(X_i | \text{parents}(X_i))$$

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Bayesian Networks: Inference

$$P(C,S,R,W,F) = P(C) P(S|C) P(R|C) P(W|R,S) P(F|R)$$

$$P(C,F) = \sum_S \sum_R \sum_W P(C,S,R,W,F)$$

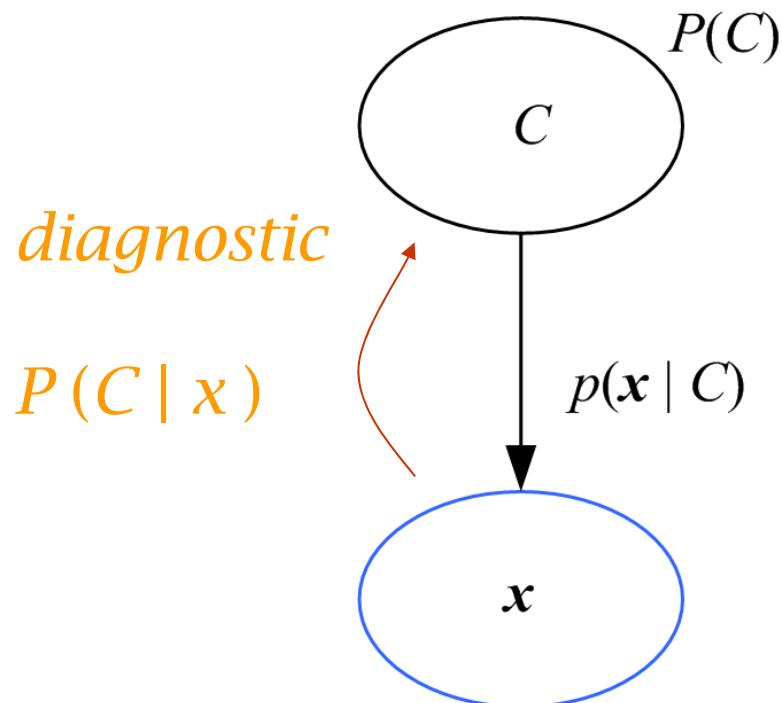
$$P(F|C) = P(C,F) / P(C) \quad \textit{Not efficient!}$$

Belief propagation (Pearl, 1988)

Junction trees (Lauritzen and Spiegelhalter, 1988)



Bayesian Networks: Classification

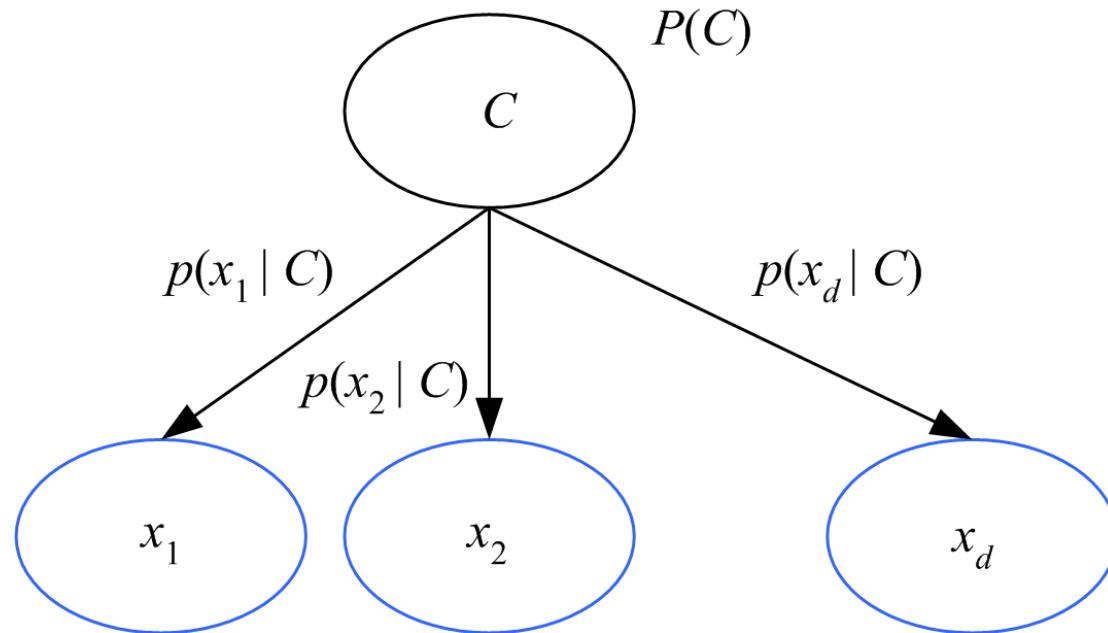


Bayes' rule inverts the arc:

$$P(C | x) = \frac{p(x | C)P(C)}{p(x)}$$



Naive Bayes' Classifier

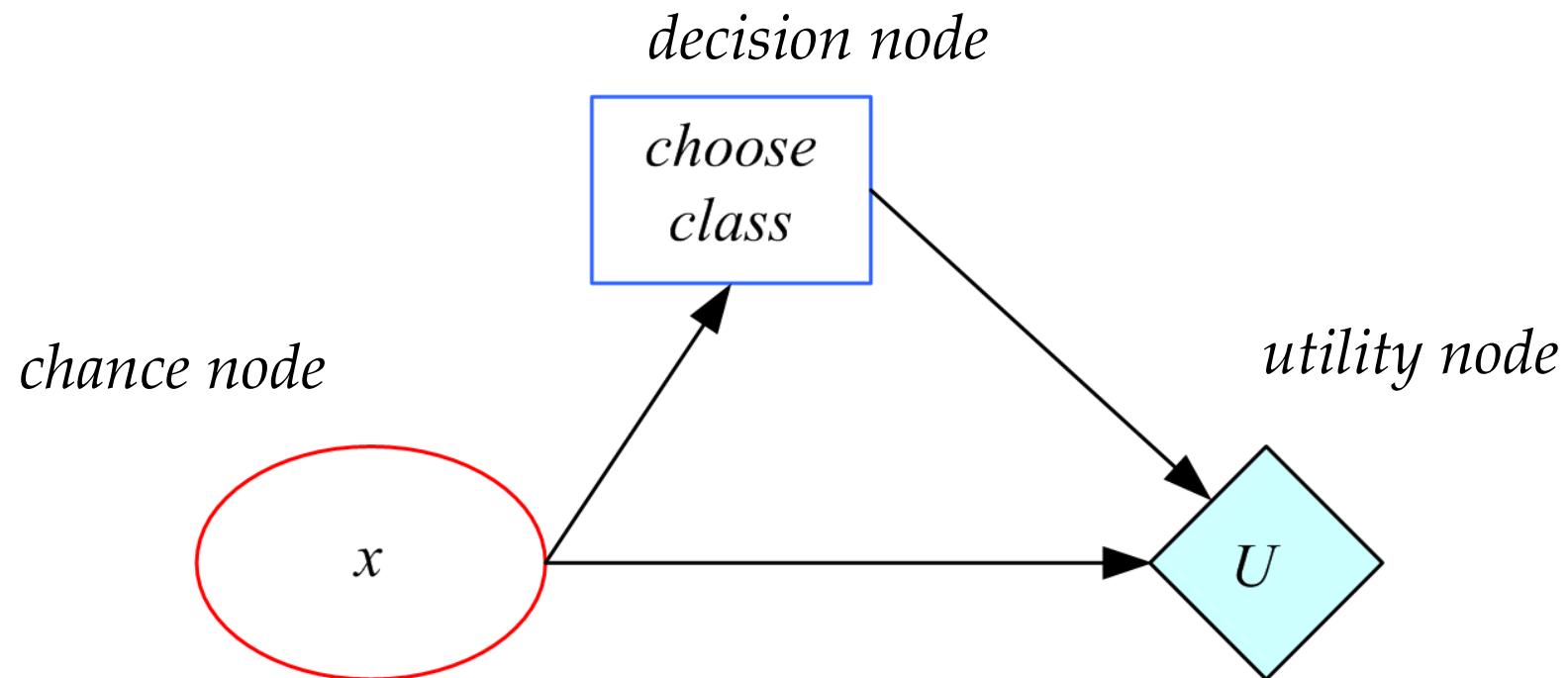


Given C , x_j are independent:

$$p(\mathbf{x}|C) = p(x_1|C) \ p(x_2|C) \dots \ p(x_d|C)$$



Influence Diagrams





Association Rules

- Association rule: $X \rightarrow Y$

- Support ($X \rightarrow Y$):

$$P(X, Y) = \frac{\#\{\text{customers who bought } X \text{ and } Y\}}{\#\{\text{customers}\}}$$

- Confidence ($X \rightarrow Y$):

$$\begin{aligned} P(Y | X) &= \frac{P(X, Y)}{P(X)} \\ &= \frac{\#\{\text{customers who bought } X \text{ and } Y\}}{\#\{\text{customers who bought } X\}} \end{aligned}$$

Apriori algorithm (Agrawal et al., 1996)