



From POP to OOP

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(Desired) Properties of software


- Is written once, modified a lot (provided that it is used).
- Is more read than written.
- Software should be written primarily for the sake of its readers (i.e. maintainers)
 - Different people
 - Different places
 - Different time



(Desired) Properties of software


- Assume you have two software systems A and B.
 - A – works, but not as readable as B
 - B – more readable than A, but has some bugs.

(This is a hypothetic situation, usually better written software has less bugs.)
- Which one is better?




(Desired) Properties of software

- Answer: B is better because most probably:
 - When modified (and this will happen soon) A will contain bugs.
 - B can be easily debugged.



A comment on our examples

- Having this in mind, our programs are
 - examples of (hopefully) well-written programs,
 - not necessarily bug free.



A word about documentation

- A software should be:
 - Self-documenting:
 - meaningful and consistent naming. Is "flag" a good name?
 - clear flow of control:
 - write as you think
 - think naturally

(things are usually straightforward, bad programmers complicate them)
 - Document everything which is not crystal clear:
 - Distinguish between:
 - external documentation, and
 - Internal documentation
 - Not over-documented.

```
int counter = 0; // A counter, initialized to zero
```

About style

- Readability is achieved by good style in the low level:
 - Clearly define and use coding conventions.
 - Small functions (≤ 30 lines)
 - Spacing and indentation
 - ...

A simple Elevator Simulator

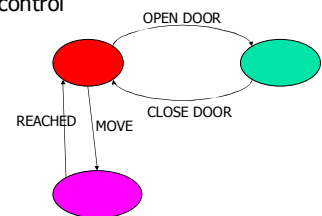
- A building:
 - Lowest floor (≤ 0)
 - Highest floor (≥ 0)
 - Number of elevators
 - Number of persons
- All elevators have the same characteristics:
 - Acceleration time (seconds)
 - Slow-down time (seconds)
 - Time between floors (seconds)

The Elevator Simulator -cont'd

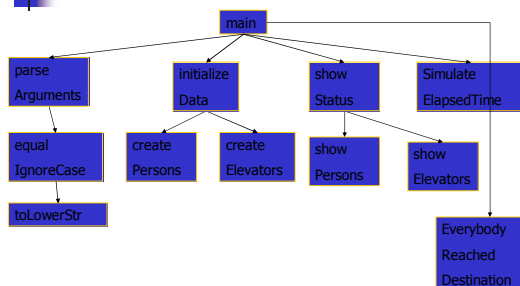
- Each Person wants to get
 - from his/her "From Floor"
 - to his/her "To Floor"
 - distributed uniformly between lowest floor and highest floor.
- All the persons are present at the beginning of the simulation
- Simulation ends when all the persons reach their destinations.

The Elevator Simulator -cont'd

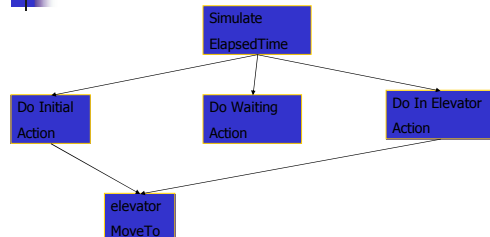
- Elevators are of the simplest from
 - No electronic control
 - No memory
 - Three states
 - STOPPED
 - DOOR-OPEN
 - MOVING



A TOP-DOWN Design





A TOP-DOWN Design-cont'd



Data Structures

- struct elevator
 - state
 - lastFloorStopped
 - movingTo
 - secondsToDestination
 - secondsInFullSpeed
- struct person
 - name
 - fromFloor
 - toFloor
 - state
 - elevator

elevators 

persons 

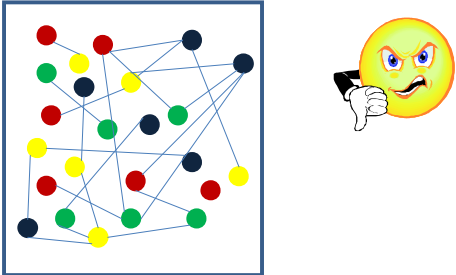
Sample code in project

ElevatorC-1-Procedural

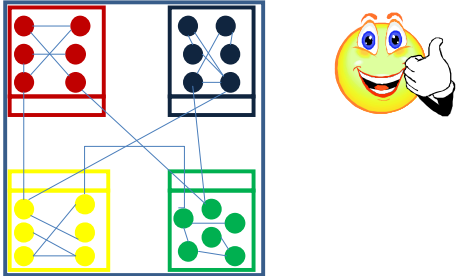
Modularization

- Goals
 - Break-down the monolithic program
 - Into modules that are
 - Coherent
 - Well decoupled (loosely coupled)
- Modules
 - Elevator
 - person
 - simulator

W/O Modularization



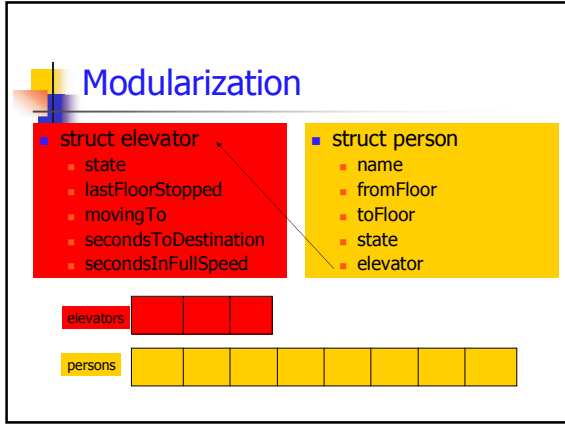
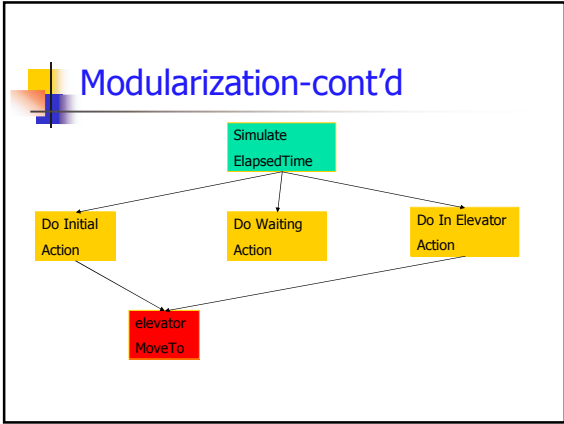
With Modularization



Modularization – cont'd

```

graph TD
    main[main] --> parse[parse Arguments]
    main --> initialize[initialize Data]
    main --> showStatus[show Status]
    main --> simulate[Simulate ElapsedTime]
    
    parse --> equal[equal IgnoreCase]
    equal --> toLower[toLowerStr]
    
    initialize --> createPersons[create Persons]
    initialize --> createElevators[create Elevators]
    
    showStatus --> showPersons[show Persons]
    showStatus --> showElevators[show Elevators]
    
    simulate --> everybody[Everybody Reached Destination]
  
```

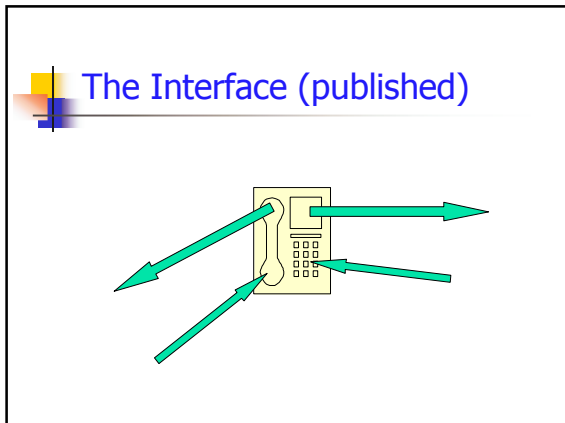


Sample code in project

ElevatorC-2-Modular

- ### Problem
- The modules are quite coherent.
 - No improvement as far as the coupling is concerned.

- ### Solution: ADT
- Abstract Data Types:**
 - Define data types in terms of their interfaces,
 - i.e. the set of possible operations on them.
 - Hide the implementation:**
 - Data structures
 - Code (this was already quite hidden if you used the keyword static appropriately)

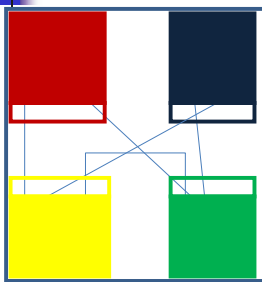


The Implementation (hidden)



Why hide implementation ?

- Is it confidential ? Sometimes.
- The principle is (0 > 1):
 - What you don't know can not hurt you.
 - The less you know (i.e. you assume) the better.



Sample code in project

ElevatorC-3-ADT

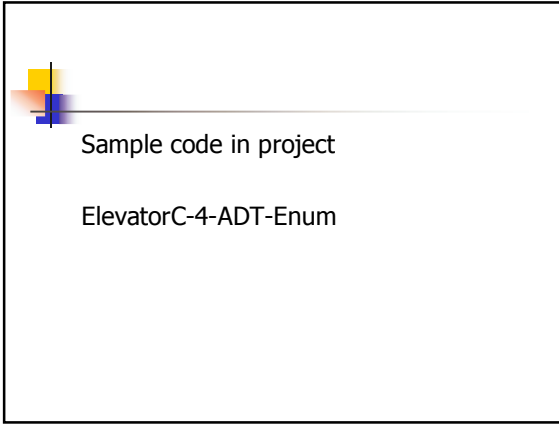
#define → enum

- More strongly typed:
 - It is possible to assign illegal values to the int variables.
 - Impossible to do this to variables of enum type
- Compiler checks for forgotten switch cases.

#define → enum

```
#define ELEVATOR_STOPPED 1
#define ELEVATOR_DOOR_OPEN 2
#define ELEVATOR_MOVING 3
```

```
typedef enum {
    ELEVATOR_STOPPED,
    ELEVATOR_DOOR_OPEN,
    ELEVATOR_MOVING
} ElevatorState;
```



Sample code in project

ElevatorC-4-ADT-Enum